



**LAKIREDDY BALI REDDY COLLEGE OF ENGINEERING**

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**L.B.Reddy Nagar, Mylavaram-521230, Krishna Dist, Andhra Pradesh, India**

### **UNIT – III**

**Digital Modulation Techniques: Wave form representation of different digital modulation techniques; Amplitude Shift Keying, Coherent Phase Shift Keying(PSK)- Binary Phase Shift Keying, Quadrature Phase Shift Keying, Differential PSK, Coherent Frequency Shift Keying, Probability of error for BASK, BPSK, BFSK.**



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**Wave form representation or A line code** is the code used for data transmission of a digital signal over a transmission line. This process of coding is chosen so as to avoid overlap and distortion of signal such as inter-symbol interference.

### **Properties of Line Coding**

**Following are the properties of line coding –**

As the coding is done to make more bits transmit on a single signal, the bandwidth used is much reduced.

For a given bandwidth, the power is efficiently used.

The probability of error is much reduced.

Error detection is done and the bipolar too has a correction capability.

Power density is much favorable.

The timing content is adequate.

Long strings of **1s** and **0s** is avoided to maintain transparency.



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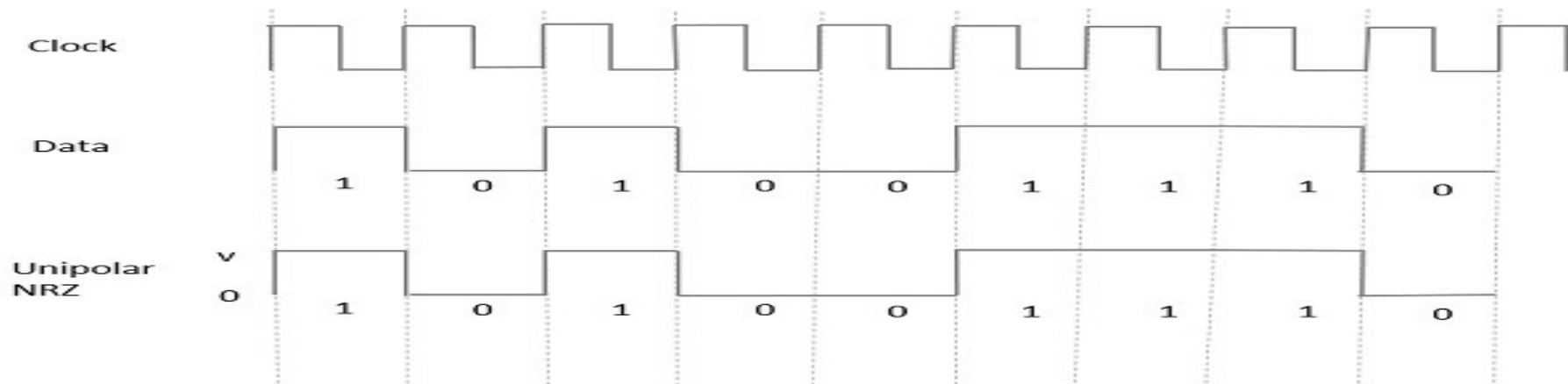
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**Types of Line Coding:** There are 3 types of Line Coding i) Unipolar Polar ii) Polar iii) Bi-polar  
**Unipolar Non-Return to Zero NRZ**



## Advantages

The advantages of Unipolar NRZ are –i) It is simple. ii) A lesser bandwidth is required.

## Disadvantages

The disadvantages of Unipolar NRZ are –i) No error correction done.

ii) Presence of low frequency components may cause the signal droop.

iii) No clock is present.

iv) Loss of synchronization is likely to occur (especially for long strings of **1s** and **0s**).



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Line codes for the electrical representations of binary data.

(a) Unipolar non-return-to-zero (NRZ) signaling (on-off signalling).

- Binary 1 – pulse, Binary 0 – no pulse

(b) Polar NRZ signaling.

- Binary 1 – Positive pulse, Binary 0 – negative pulse

(c) Unipolar return-to-zero (RZ) signaling.

- Binary 1 – Positive half width pulse ,  
Binary 0 – no pulse

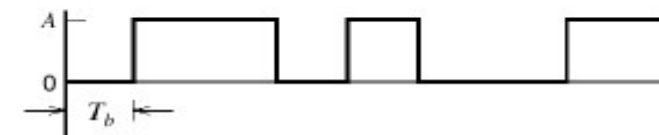
(d) Bipolar RZ signaling.

- Binary 1 – Alternative + and - pulses,  
Binary 0 – no pulse

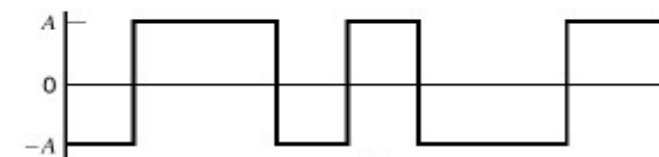
(e) Split-phase or Manchester code.

- Binary 1 – Positive to negative transition pulse with half symbol width, Binary 0 – Negative to positive pulse with half symbol width

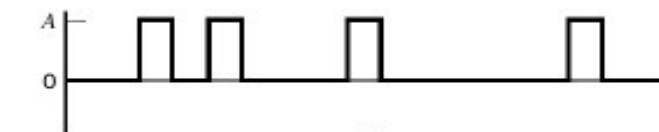
Binary data 0 1 1 0 1 0 0 1



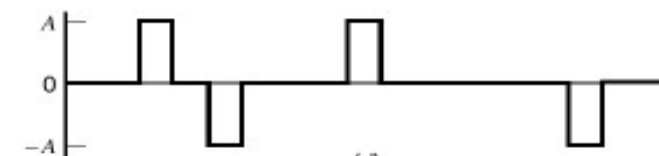
(a)



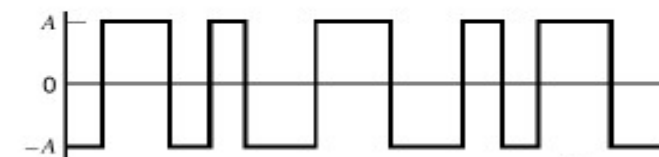
(b)



(c)



(d)



(e)

Time →



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## Digital Modulation

- In **binary** signaling, the modulator produces one of **two distinct signals** in response to bit of source data at a time. By shifting the parameters either Amplitude or Phase or frequency of carrier with reference to the binary data digital modulation can be achieved.
- Binary modulation types
  - Binary ASK
  - Binary PSK (BPSK)
  - Binary FSK
  - Binary QPSK
  - DPSK
- Coherent Detection
- Non coherent Detection



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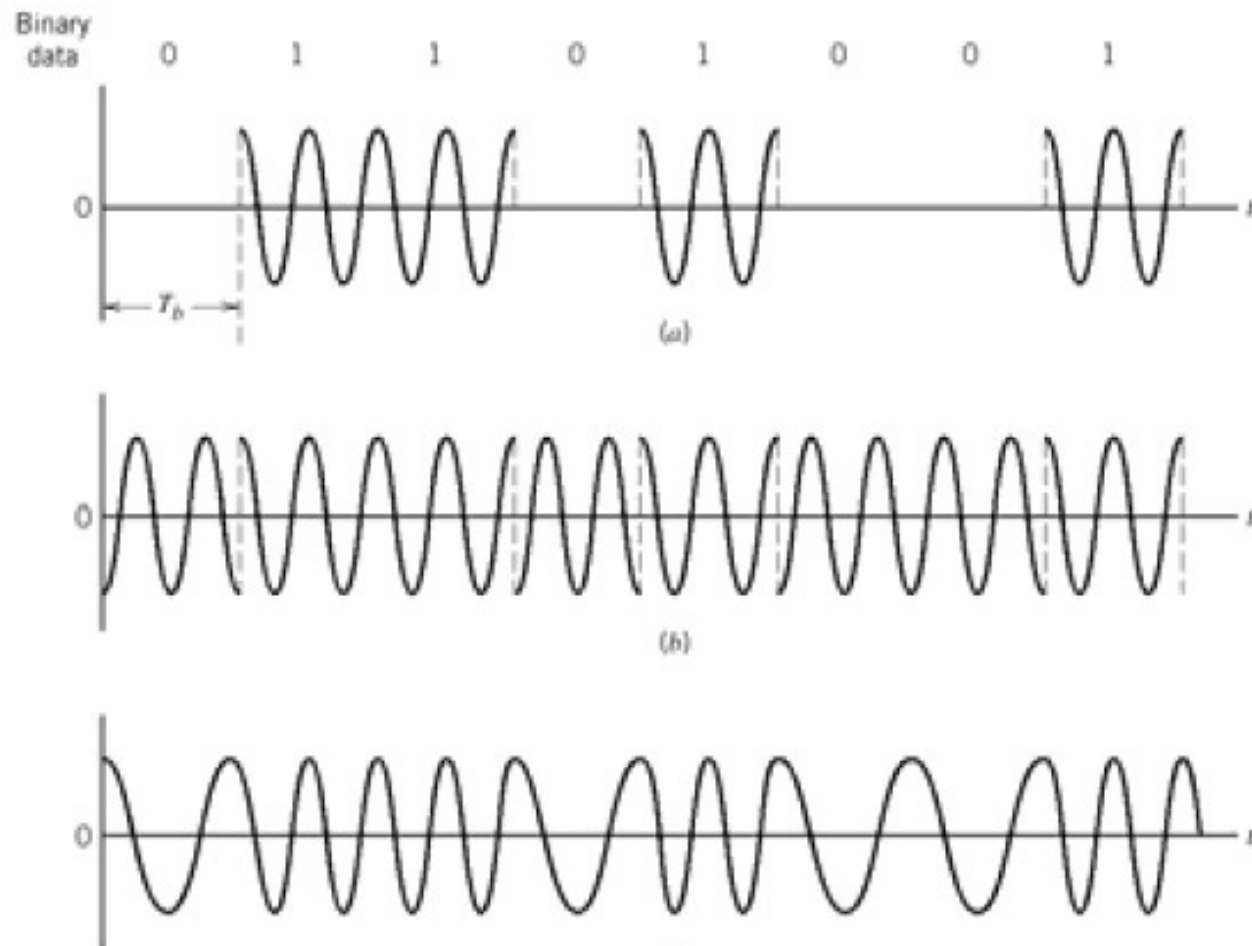
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- Types

- ASK

- PSK

- FSK





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## Binary Amplitude Shift Keying

- In transmitter the binary data sequence is given to an on-off encoder.
- Which gives an output  $E_b$  volts for symbol 1
- and 0 volt for symbol 0.
- The resulting binary wave and sinusoidal carrier  $\phi_1(t)$  are applied to a product modulator. The desired BASK wave is obtained at the modulator output.
- In demodulator, the received noisy BASK signal  $x(t)$  is apply to correlator with coherent reference signal  $\phi_1(t)$ . The correlator output  $x$  is compared with threshold  $\lambda$ .
- If  $x > \lambda$  the receiver decides in favour of symbol 1. If  $x < \lambda$  the receiver decides in favour of symbol 0.



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- The binary ASK may be expressed as

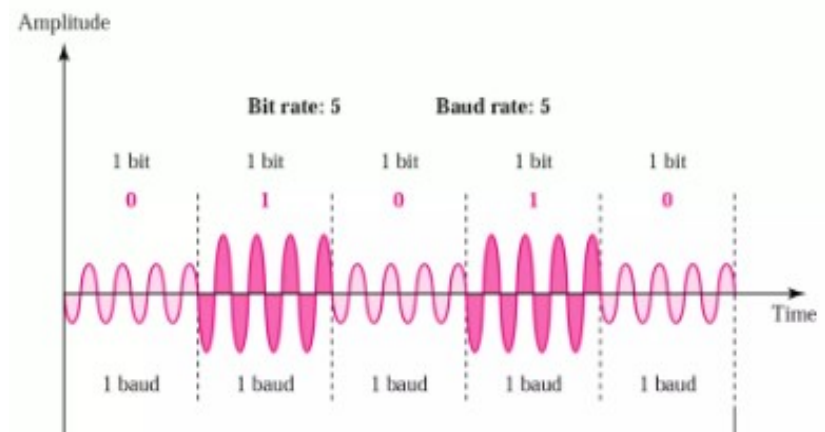
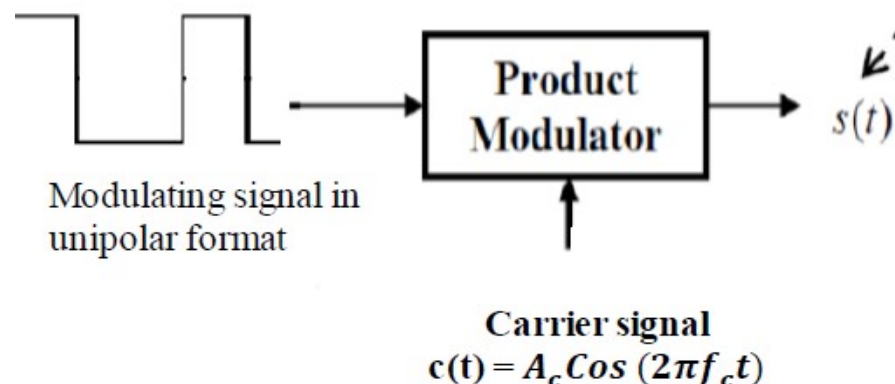
$$s(t) = \begin{cases} s_1(t) = A \cos(2\pi f_c t) & \text{For transmitted bit '1'} \\ s_1(t) = 0 \text{ or } A_2 \cos(2\pi f_c t) & \text{For transmitted bit '0'} \end{cases}$$



1 0 0 1 0 Random input signal

BASK Modulated signal

## ASK (AMPLITUDE SHIFT KEYING)





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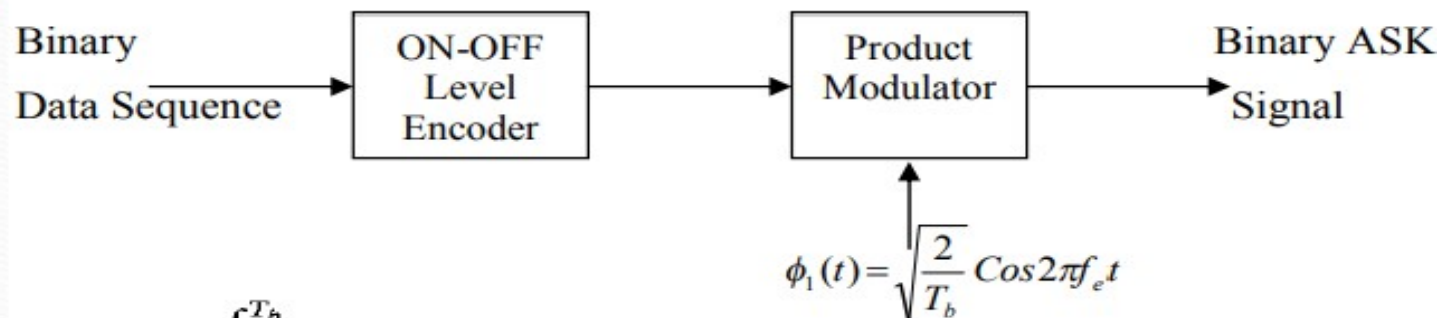
- For binary '1'

$$s_1(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t)$$

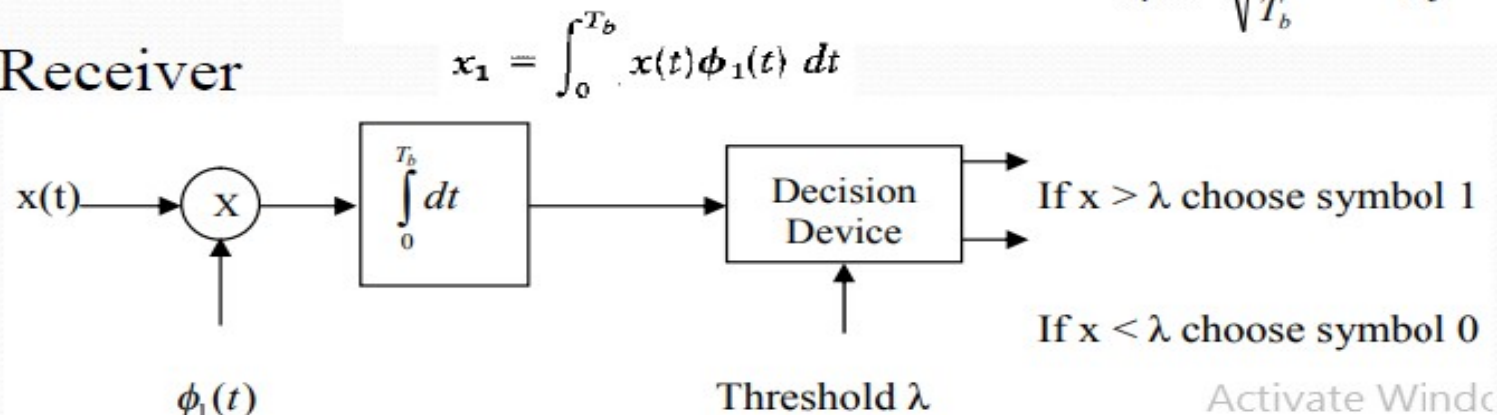
- For binary '0'

$$s_2(t) = 0 \quad 0 \leq t < T_b$$

- Transmitter



- Receiver



Activate Windows

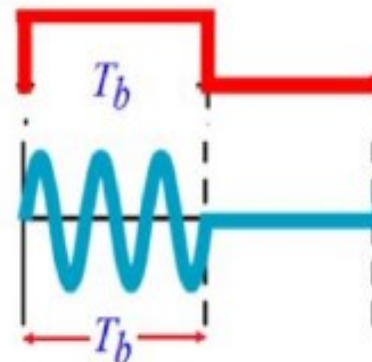
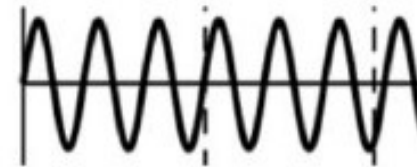
In digital communication literature, the usual practice is to assume that the carrier  $c(t) = A_c \cos 2\pi f_c t$  has unit energy measured over one symbol (bit) duration.

The power of the carrier signal  $P_c = \frac{A_c^2}{2}$  watts.

Energy for a duration  $T_b$  pulse  $E_b = T_b P_c = \frac{A_c^2}{2} T_b$

or  $A_c = \sqrt{\frac{2E_b}{T_b}}$

$$c(t) = A_c \cos 2\pi f_c t = \sqrt{\frac{2E_b}{T_b}} \cos 2\pi f_c t$$



$\sqrt{\frac{2}{T_b}} \cos 2\pi f_c t$  referred to as **basis function** (Orthonormal)

Now  $s(t)|_{ASK} = \sqrt{E_b} \sqrt{\frac{2}{T_b}} \cos(2\pi f_c t) = \sqrt{E_b} \phi_1(t)$ ,  $0 \leq t \leq T_b$   
 where  $\phi_1(t)$  = orthogonal signal & is used to Rept The signal.

Then for  $b(t)$  = Binary Symbol 1  $= s_1(t) = s(t)|_{ASK} = \sqrt{E_b} \phi_1(t)$   $\left. \begin{matrix} 0 \leq t \leq T_b \\ 0 \leq t \leq T_b \end{matrix} \right\}$   
 " "  $0 = s_2(t) = s(t)|_{ASK} = 0$

**BASK** In BASK a sinusoidal carrier is simply gated on and off by the bit sequence to be transmitted.

A binary amplitude-shift keying (BASK) signal can be defined as

$$s(t) = A_c m(t) \cos 2\pi f_c t, \quad 0 \leq t \leq T_b$$

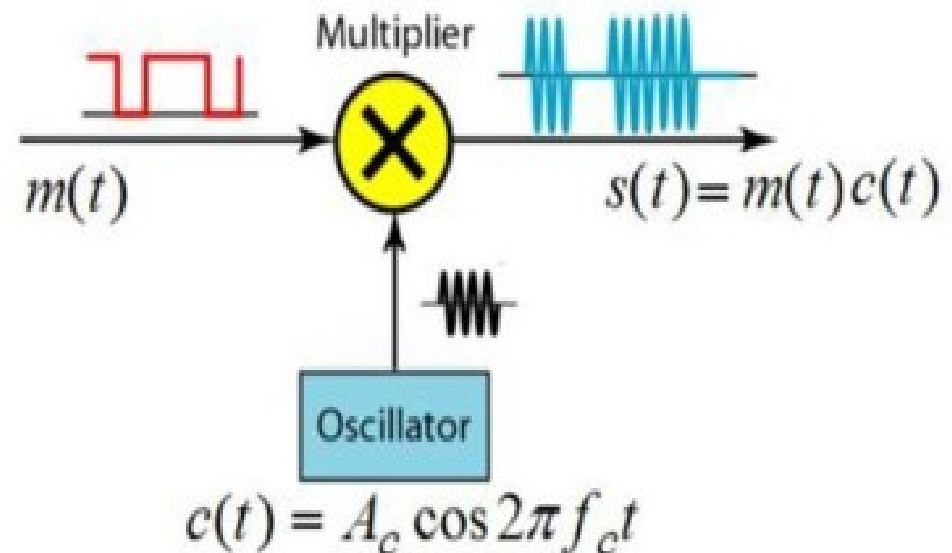
where  $A_c$  is a constant amplitude

$m(t)$  is digital information signal

$m(t) = 1$  or  $0$

$f_c$  is carrier frequency

$T_b$  is the bit duration



$$s(t) = \begin{cases} s_1(t) = A_c \cos 2\pi f_c t \\ \quad = \sqrt{\frac{2E_b}{T_b}} \cos 2\pi f_c t, & 0 \leq t \leq T_b : \text{Logic 1} \\ s_2(t) = 0, & \text{Else : Logic 0} \end{cases}$$

Average Energy per bit

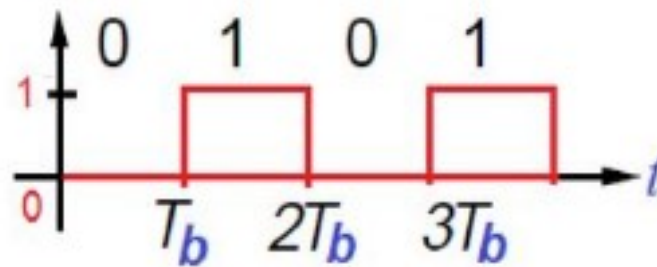
$E_b$

# Spectrum of BASK

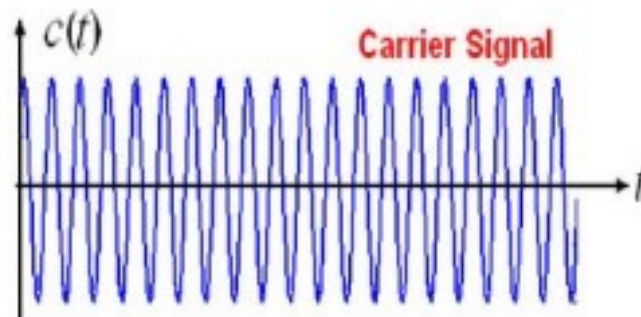
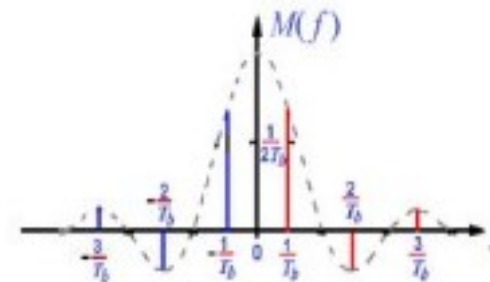
$$s(t) = A_c m(t) \cos 2\pi f_c t, \quad 0 \leq t \leq T_b$$

$$S(f) = \frac{A_c}{2} M(f + f_c) + \frac{A_c}{2} M(f - f_c)$$

$m(t)$



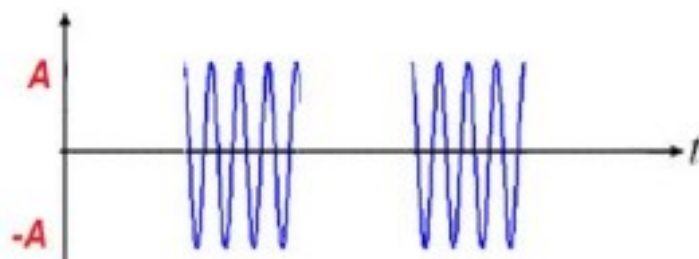
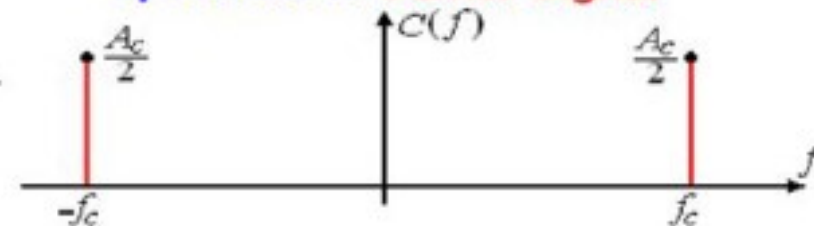
FT



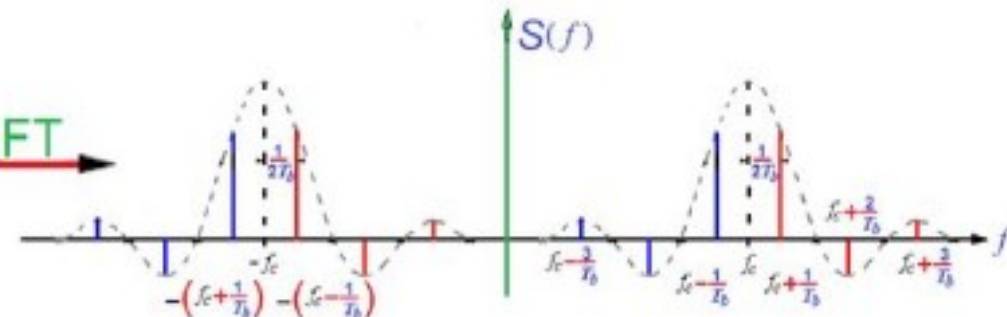
Carrier Signal

FT

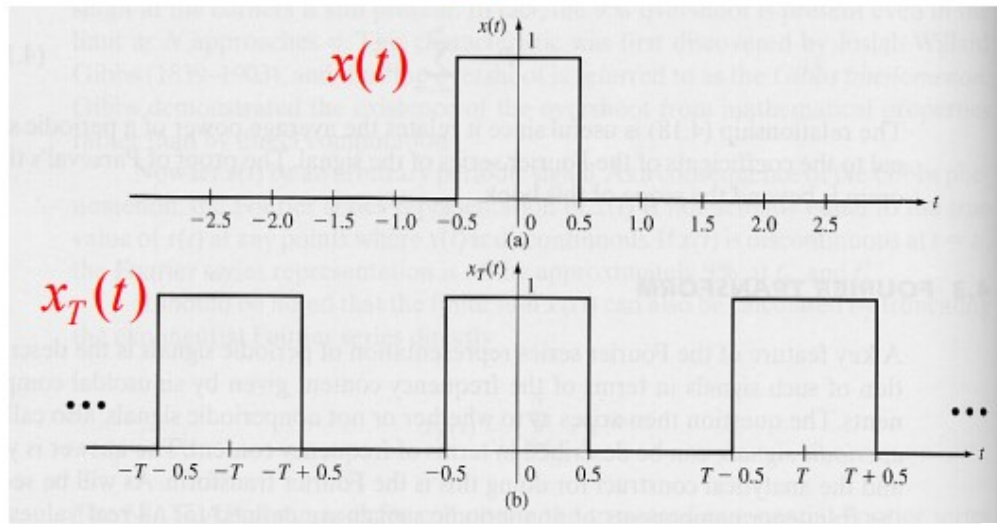
Spectrum of Carrier Signal



FT



## Frequency Content of the Rectangular Pulse



$$x(t) = \lim_{T \rightarrow \infty} x_T(t)$$

- Since  $x_T(t)$  is periodic with period  $T$ , we can write

$$x_T(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t}, \quad t \in \mathbb{R}$$

where

$$c_k = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jk\omega_0 t} dt, \quad k = 0, \pm 1, \pm 2, \dots$$

- For  $k = 0$ :

$$c_0 = 1/T \quad \rightarrow \text{sinc}(x) = \frac{\sin x}{x}$$

- For  $k = \pm 1, \pm 2, \dots$ :

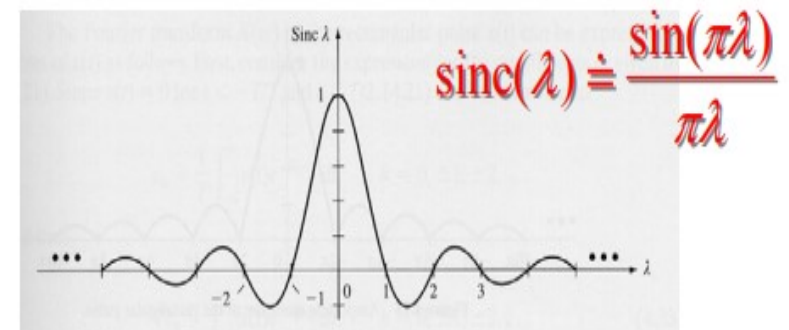
$$c_k = \frac{2}{k\omega_0 T} \sin\left(\frac{k\omega_0}{2}\right) = \frac{1}{k\pi} \sin\left(\frac{k\omega_0}{2}\right)$$

$\omega_0 = 2\pi/T$

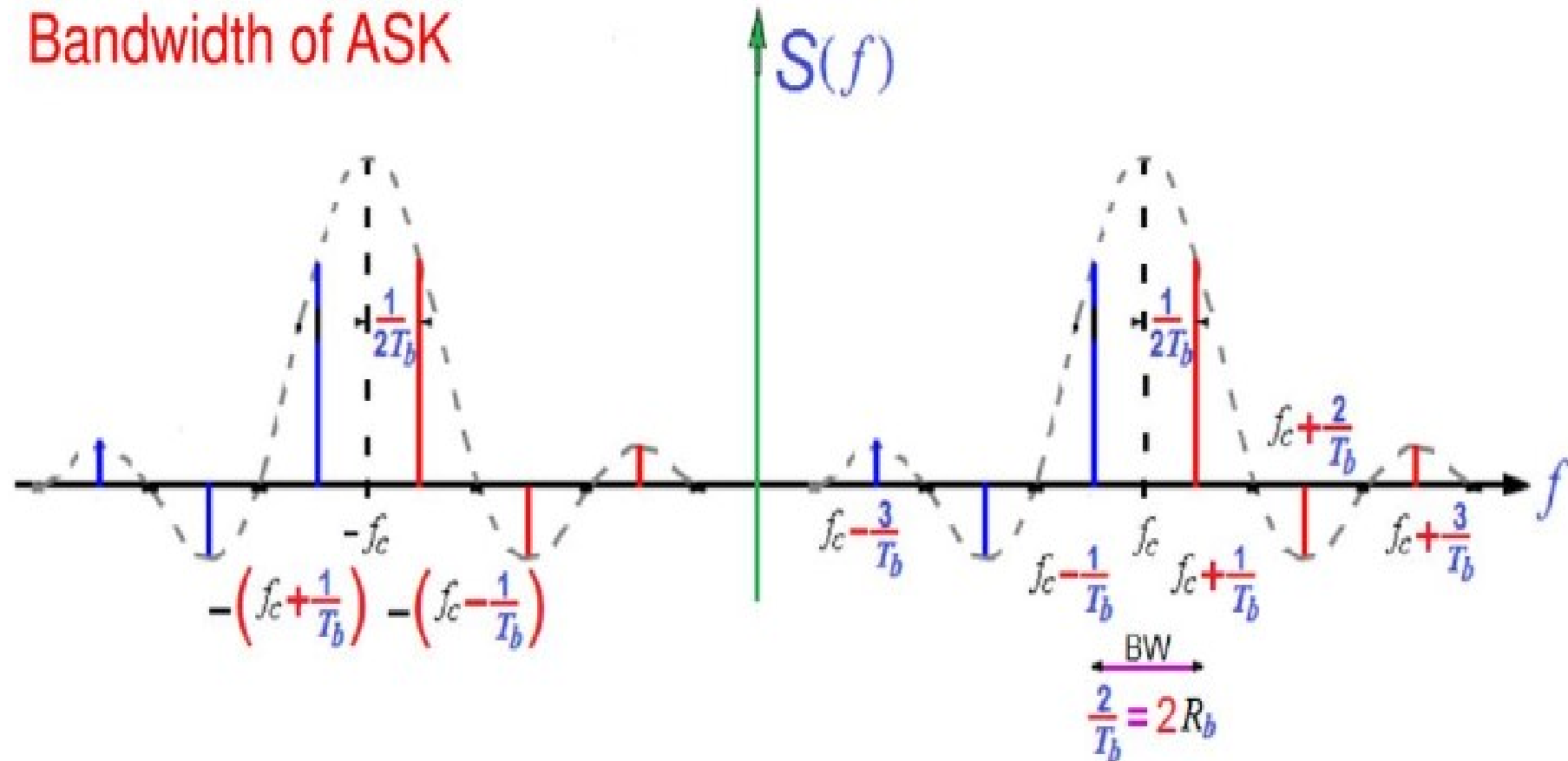
- It can be easily shown that

$$\lim_{T \rightarrow \infty} T c_k = \text{sinc}\left(\frac{\omega}{2\pi}\right), \quad \omega \in \mathbb{R}$$

where

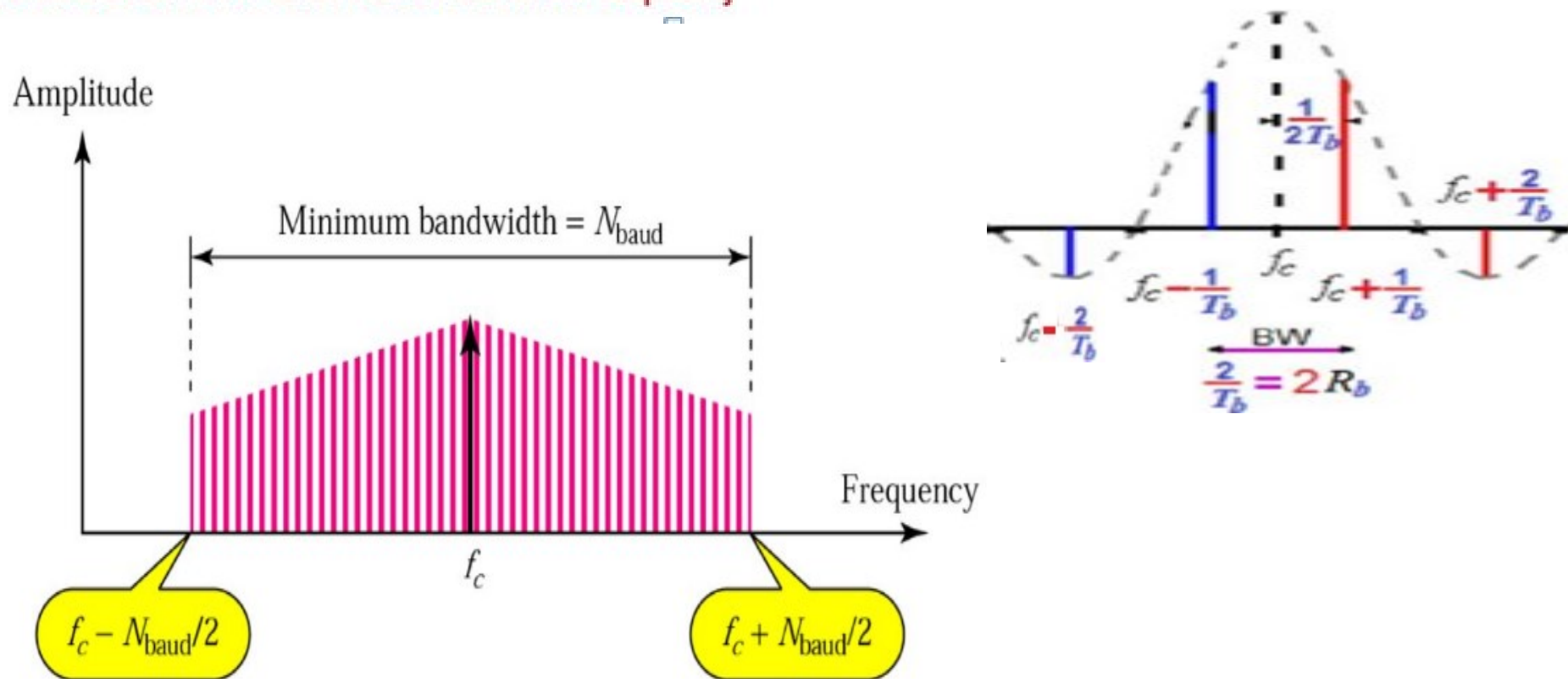


## Bandwidth of ASK



- The first, bandwidth in hertz, refers to the range of frequencies in a composite signal or the range of frequencies that a channel can pass.
- The second, bandwidth in bits per second, refers to the speed of bit transmission in a channel or link. Often referred to as Capacity

- The second, bandwidth in bits per second, refers to the speed of bit transmission in a channel or link. Often referred to as Capacity



With ASK, the bit rate is equal to the minimum Nyquist bandwidth

$$BW = \frac{f_b}{1} = f_b; \text{ Baud} = \frac{f_b}{1} = f_b$$

Bit rate is the number of bits per second. Baud rate is the number of signal units per second. Baud rate is less than or equal to the bit rate.



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**Ex1: Find the minimum bandwidth for an ASK signal transmitting at 2000 bps.**

**Ans:** In ASK the baud rate and bit rate are the same.

The baud rate is therefore 2000.

An ASK signal requires a minimum bandwidth equal to its baud rate.

Therefore, the minimum bandwidth is 2000 Hz

**Ex2:** Given a bandwidth of 5000 Hz for an ASK signal, what are the baud rate and bit rate?

In ASK the baud rate is the same as the bandwidth, which means the baud rate is 5000.

But because the baud rate and the bit rate are also the same for ASK, the bit rate is 5000 bps.



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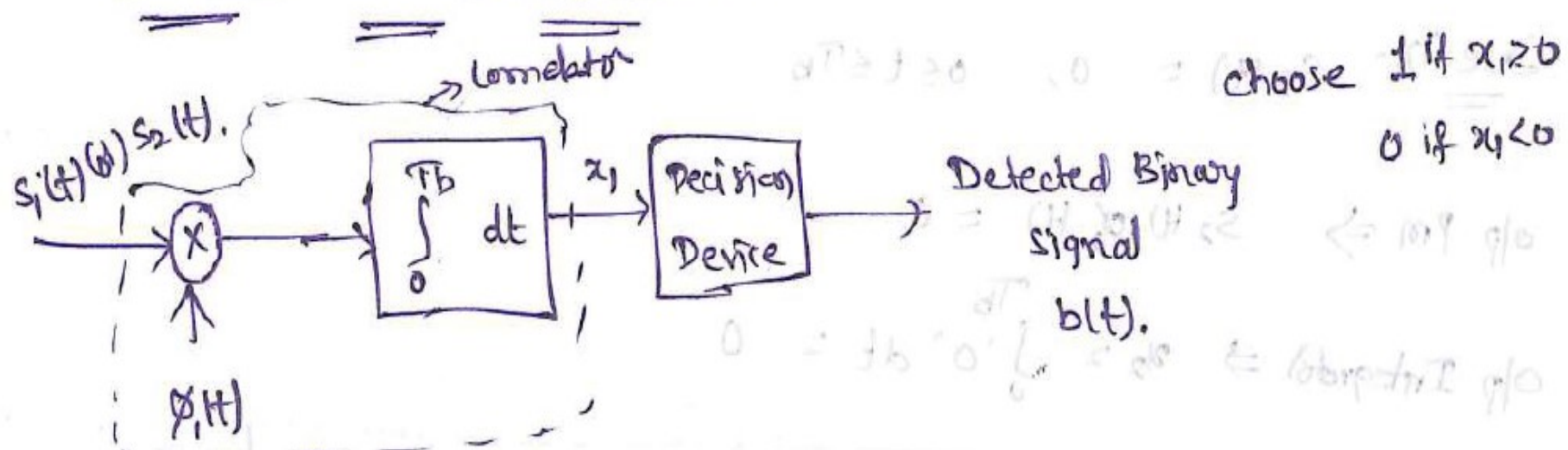
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(i) Coherent ASK Demodulator :-



o/p of PM  $\Rightarrow s_1(t) \cdot \phi_1(t) \Rightarrow \sqrt{E_b} \phi_1^2(t)$

o/p of Integrator  $\Rightarrow x_1 = \int_0^{T_b} \sqrt{E_b} \phi_1^2(t) dt$



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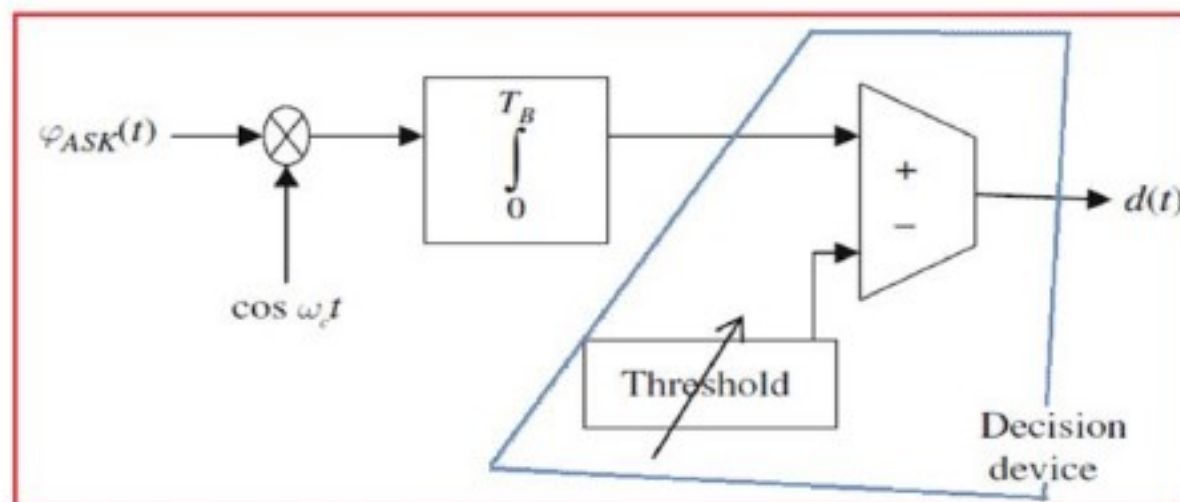
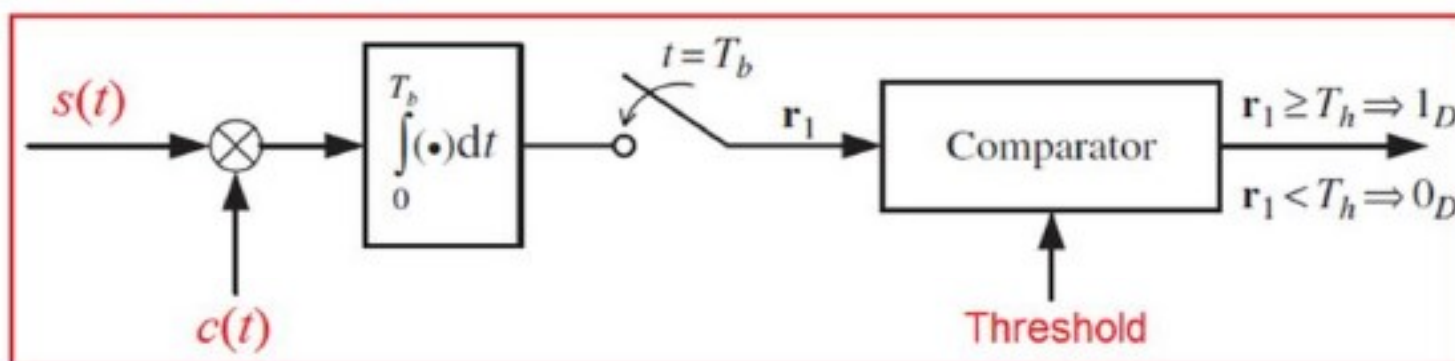
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## ASK Receiver





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## Coherent Detection

- An estimate of the channel phase and attenuation is recovered. It is then possible to reproduce the transmitted signal and demodulate.
- Requires a replica carrier wave of the same frequency and phase at the receiver.
- The received signal and replica carrier are cross-correlated using information contained in their amplitudes and phases.
- Also known as synchronous detection

## Non-Coherent Detection

- Requires no reference wave; does not exploit phase reference information (envelope detection)
  - Differential Phase Shift Keying (DPSK)
  - Frequency Shift Keying (FSK)
  - Amplitude Shift Keying (ASK)
  - Non coherent detection is less complex than coherent detection (easier to implement), but has worse performance.



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- \* The BPF Passes only carrier signal  $f_c$
- \* Envelope detector generates high o/p voltage when carrier present.  
 " " " low " " " Absent.
- \* The decision device basically regenerative repeater, ~~it~~ ~~is~~ ~~not~~ ~~an~~ ~~adder~~
  - if  $ED > \text{Threshold} \Rightarrow$  Pulse generated with high voltage  $0 \leq t \leq T$
  - if  $ED < \text{"} \Rightarrow$  " " " zero "  $0 \leq t \leq T$



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## ASK Space diagram

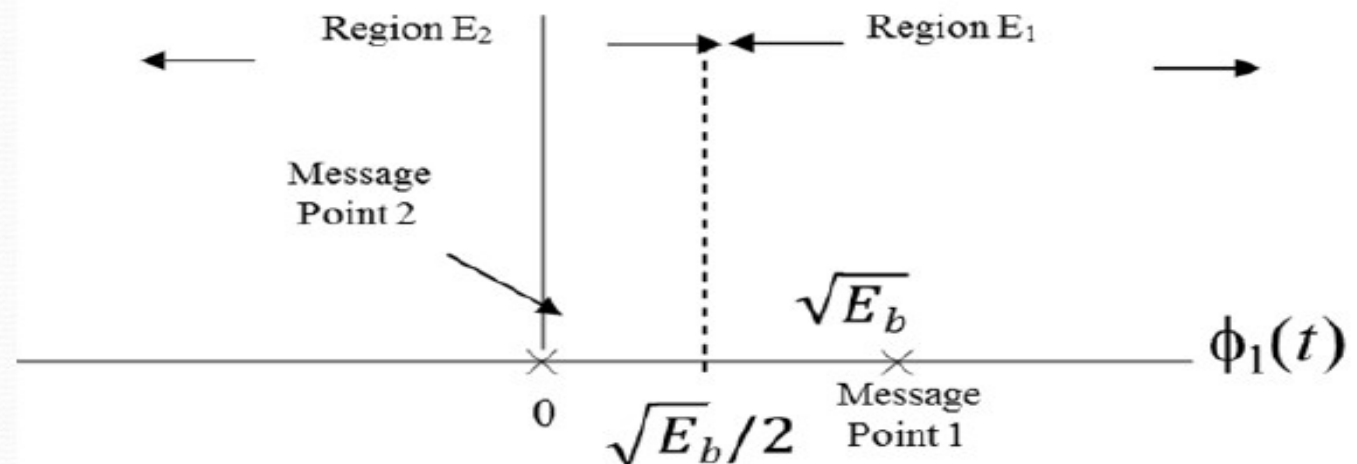
- For binary '1'

$$s_1(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t)$$

- For binary '0'

$$s_2(t) = 0 \quad 0 \leq t < T_b$$

$$x_j = \int_0^T x(t) \phi_j(t) dt$$
$$= s_{ij} + w_i, \quad j = 1, 2, \dots, N$$





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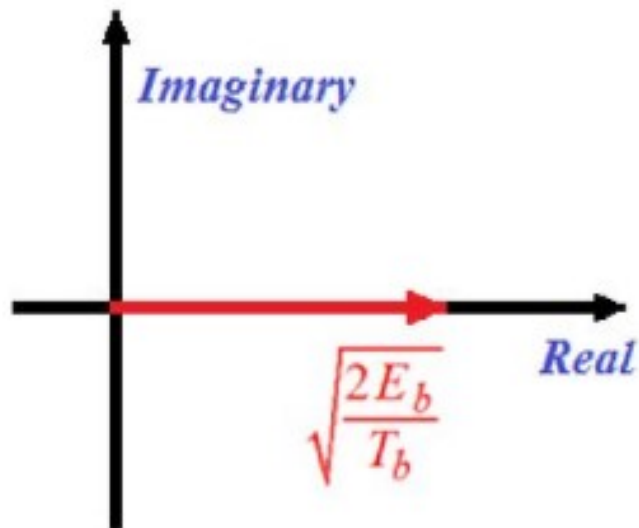
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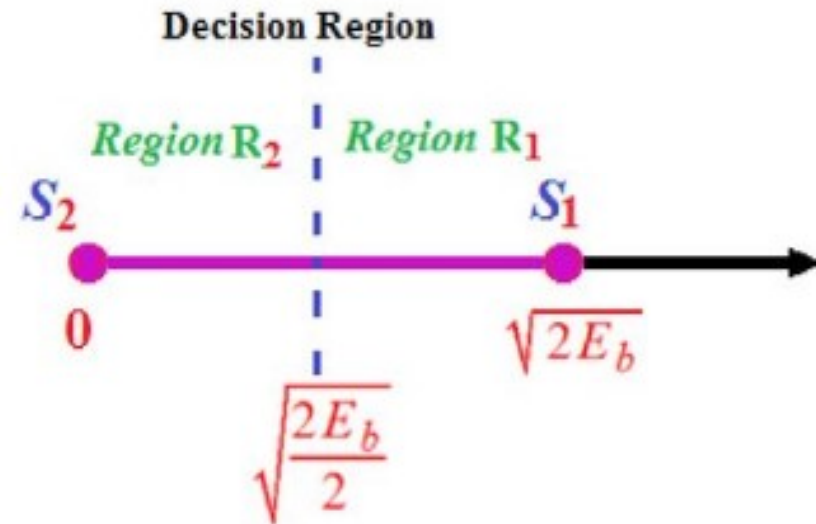
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Signal Space:

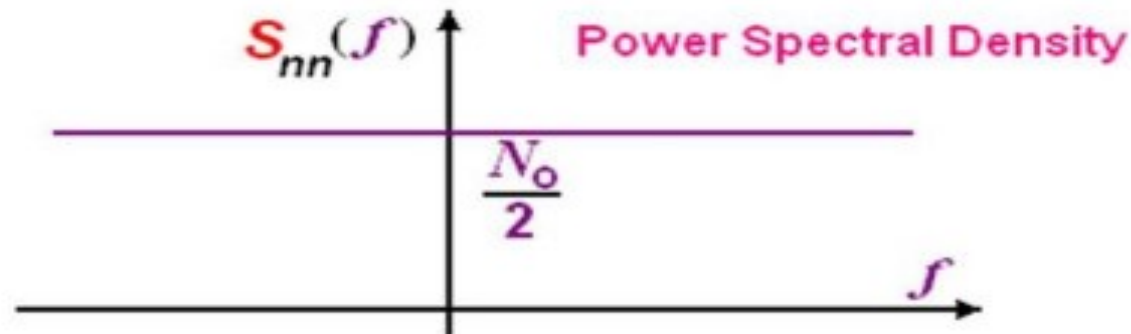
ASK Constellation Diagram



$$s(t) = \sqrt{\frac{2E_b}{T_b}} \cos 2\pi f_c t + j 0 \quad 0 \leq t \leq T_b$$

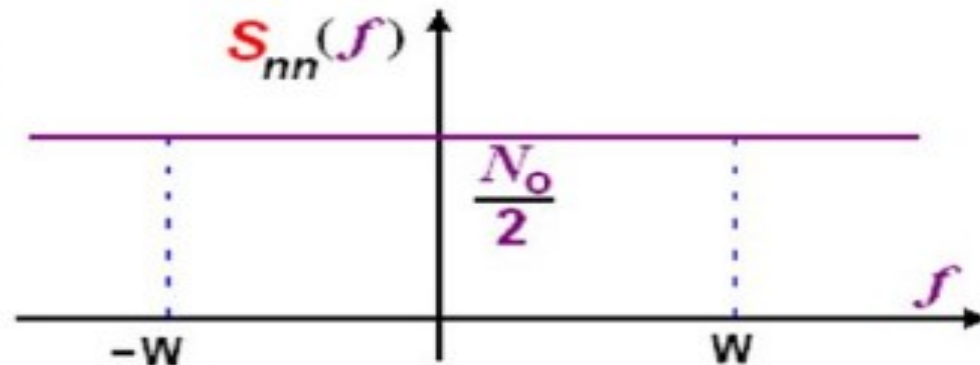


## Additive White Noise



Average Power of Additive White Noise

$$\begin{aligned} P_n &= \int_{-W}^W S_{nn}(f) df \\ &= \frac{N_0}{2} 2W = N_0 W \end{aligned}$$



Noise is assumed to be uncorrelated with the signal

# Gaussian Noise

- Let  $\eta(t)$  denote a noisy signal.
- The values of noisy signal are **unpredictable** and only a probability can be associated to them,

$$\Pr\{n_1 < \eta(t) \leq n_2\}$$

- The most common type of noise found in a communication system is **Gaussian** with PDF

$$P_{\eta(t)}(n) = \frac{1}{\sqrt{2\pi\sigma_{\eta}^2}} e^{-\frac{1}{2}\left(\frac{n-\mu_{\eta}}{\sigma_{\eta}}\right)^2}$$

where  $\mu_{\eta} = E\{\eta(t)\}$  : Mean value , and

$$\sigma_{\eta}^2 = E\left\{\left(\eta(t) - \mu_{\eta}\right)^2\right\} : \text{Variance}$$



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Probability of error  $P_e$  of binary 0

$$P_e = \int_{d_{ik}/2}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2\sigma^2}(x)^2\right) dx$$

$$P_{e0} = \frac{1}{\sqrt{\pi N_0}} \int_{\frac{\sqrt{E_b}}{2}}^{\infty} \exp\left[-\frac{(x-0)^2}{N_0}\right] dx$$

$$\text{Let } Z = \frac{x}{\sqrt{N_0}} \quad P_{e0} = \frac{1}{\pi} \int_{\frac{\sqrt{E_b}}{2\sqrt{N_0}}}^{\infty} \exp(-z^2) dz$$

$$P_{e0} = \frac{1}{2} \operatorname{erfc}\left(\sqrt{\frac{E_b}{4N_0}}\right)$$

Similarly for binary '1'

$$P_{e1} = \frac{1}{2} \operatorname{erfc}\left[\sqrt{\frac{E_b}{4N_0}}\right]$$

$$\text{The total probability of error} = \frac{1}{2}[P_{e0} + P_{e1}] \quad P_e = \frac{1}{2} \operatorname{erfc}\left(\sqrt{\frac{E_b}{4N_0}}\right)$$

$$\text{Also } P_e = \frac{1}{2} \operatorname{erfc}\left(\frac{d_{ik}}{2\sqrt{N_0}}\right)$$

## Error Performance: Bit Error Rate (BER)

The BASK signal at the receiver in the presence of noise is given by

$$r(t) = \alpha s(t) + n(t)$$

where  $\alpha$  is attenuation introduced by Txion channel. Assume  $\alpha = 1$ .

$n(t)$  is AWGN with power spectral density  $\frac{N_0}{2}$  W/Hz.

Then the Bit Error Rate for ASK is given by

$$\text{BER}_{\text{ASK}} = Q\left(\sqrt{\frac{E_b}{N_0}}\right)$$

where  $E_b = \frac{A_c^2 T_b}{4}$ , where again  $E_b$  is the average energy bit.

**Ex:** Binary data is transmitted using ASK through a channel that adds white Gaussian noise with power spectral density  $N_0 = 10^{-11}$  W / Hz. Determine the amplitude of a received carrier burst to provide a  $\text{BER} = 10^{-5}$  for the following data rates  
(a) 300 bps; (b) 3kbps; (c) 9.6 kbps

**Ans:** The Bit Error Rate for ASK is given by  $\text{BER}_{\text{ASK}} = Q\left(\sqrt{\frac{E_b}{N_0}}\right)$

To achieve a  $\text{BER} = 10^{-5}$   $\sqrt{\frac{E_b}{N_0}} = 4.27 \Rightarrow \frac{E_b}{N_0} = 4.27^2 = 18.233$

$$N_0 = 10^{-11}; \quad E_b = 18.233 \times 10^{-11}$$



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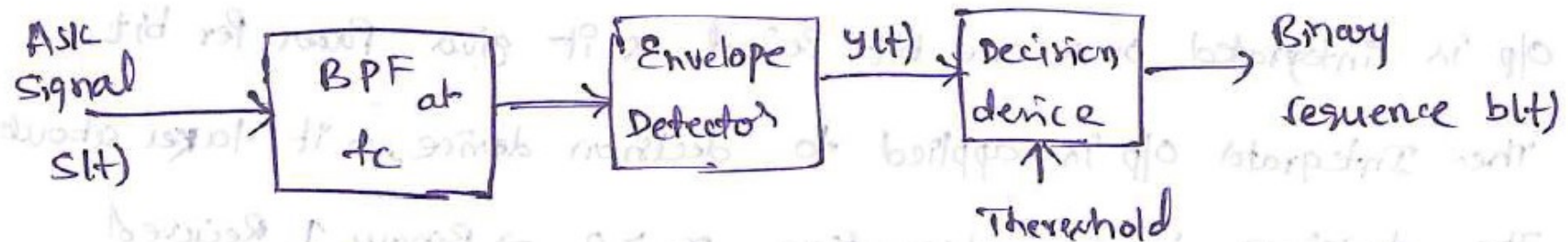
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(ii) Non Coherent Detection :-



\* The BPF Passes only carrier signal ' $f_c$ '

\* Envelope detector generates high o/p voltage when carrier is present.

" " " low " " Absent.

\* The decision device basically regenerative repeater, ~~it~~ ~~generates~~

if  $ED > \text{Threshold} \Rightarrow$  pulse generated with high voltage  $0 \leq t \leq T$   
 if  $ED < \text{Threshold} \Rightarrow$  " " " zero "  $0 \leq t \leq T$



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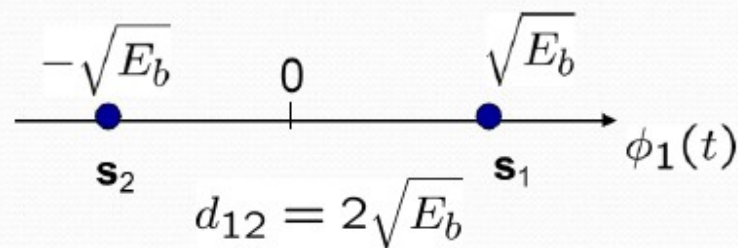
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## Binary Phase-Shift Keying (BPSK)

- A binary PSK system is therefore characterized by having a **signal space** that is **one-dimensional** (i.e.  $N=1$ ), and with two message points. The pair of signals differ by phase shift of  $180^\circ$



**Coherent Binary PSK** • In a coherent binary PSK system, the pair of signals,  $s_1(t)$  and  $s_2(t)$ , used to represent binary symbols 1 and 0, respectively, are defined by

- $S_i(t) = s_{i1}\phi_1(t)$  for  $i=1,2$
- $S_1(t) = s_{11}\phi_1(t)$  for  $i=1$
- $S_2(t) = s_{21}\phi_1(t)$  for  $i=2$

$$s_1(t) = \sqrt{E_b}\phi_1(t)$$

$$s_2(t) = -\sqrt{E_b}\phi_1(t)$$

$$\phi_1(t) = \sqrt{\frac{2}{T_b}} \cos(2\pi f_c t)$$

$$0 \leq t < T_b$$



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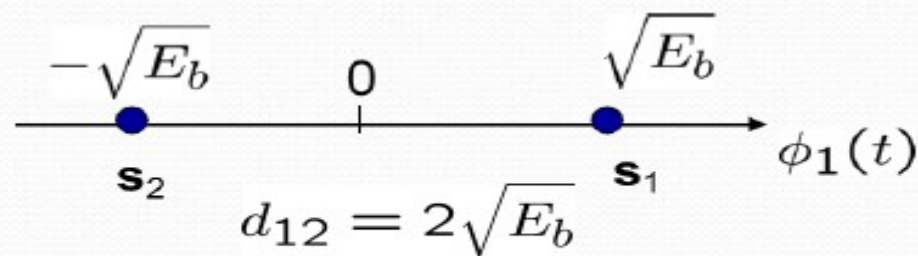
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$$0 \leq t < T_b$$



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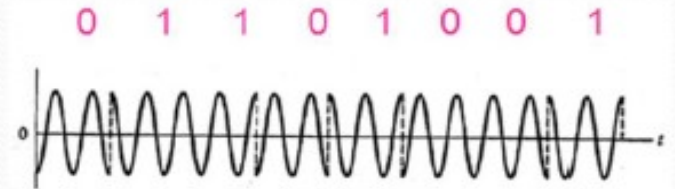
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- For Binary '1'  $s_1(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t)$
- For Binary '0'  $s_2(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t + \pi)$
- $T_b$  is bit duration  $s_2(t) = -\sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t)$
- The pair of signals differ by phase shift of  $180^\circ$
- $f_c$  carrier frequency, chosen to be  $n_c/T_b$  for some fixed integer  $n_c$
- $E_b$  is transmitted signal energy per bit,  $\int_0^{T_b} s_1^2(t) dt = \int_0^{T_b} s_2^2(t) dt = E_b$

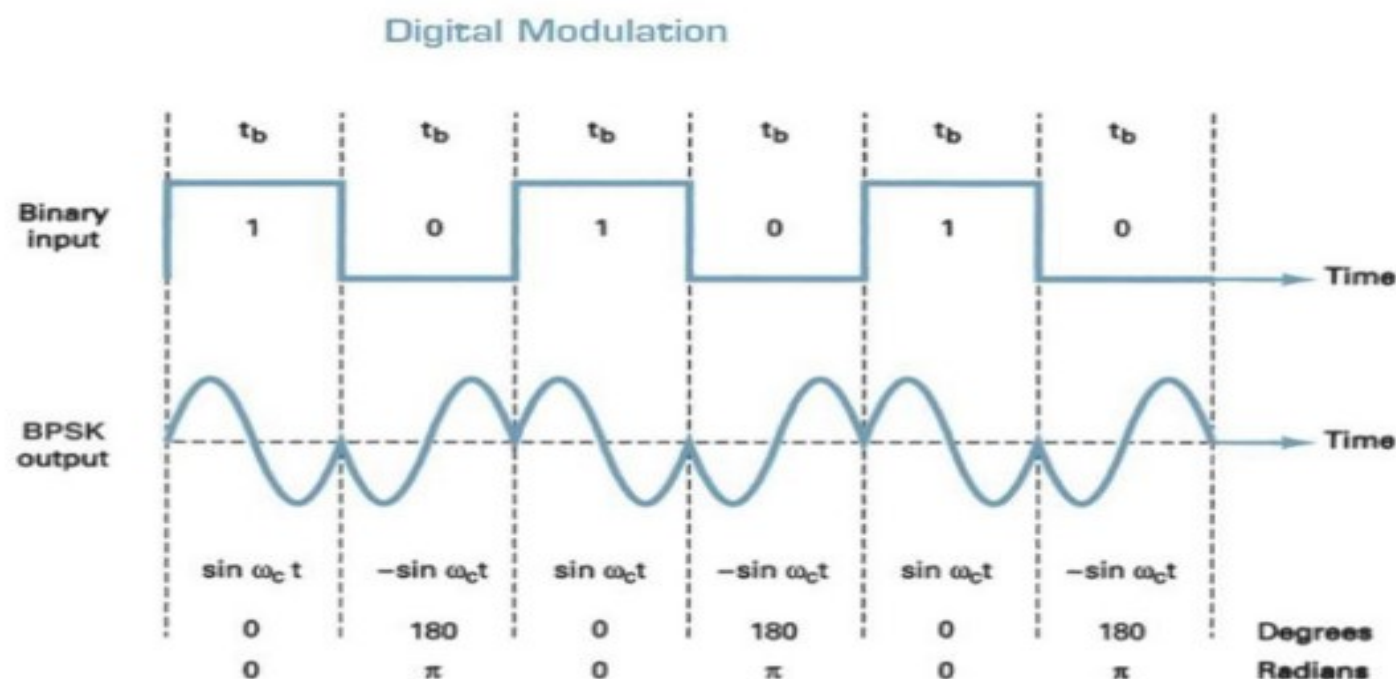


$$0 \leq t < T_b$$

## BPSK

- Phase-shift keying (PSK) is another form of angle-modulated, constant-amplitude digital modulation.
- BPSK is a form of square-wave modulation of a *continuous wave (CW) signal*.
- Vary the phase shift of the carrier signal to represent digital data.

$$s(t) = \begin{cases} s_1(t) = \sqrt{\frac{2E_b}{T_b}} \cos 2\pi f_c t, & \text{for Symbol '1'} \\ s_2(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t + \pi) = -\sqrt{\frac{2E_b}{T_b}} \cos 2\pi f_c t, & \text{for Symbol '0'} \end{cases}, 0 \leq t \leq T_b$$





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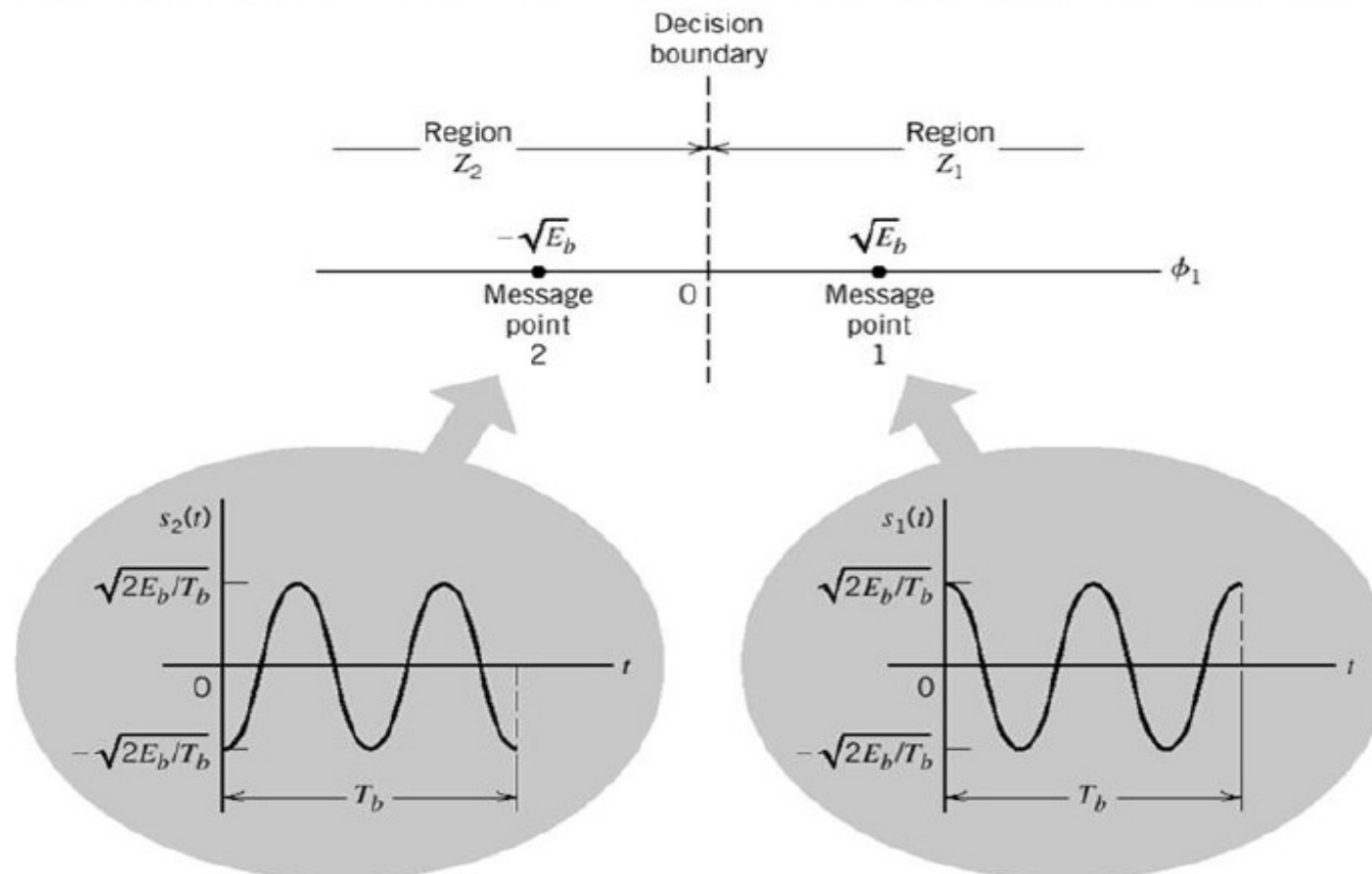
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## Signal Space Representation for BPSK

- BPSK





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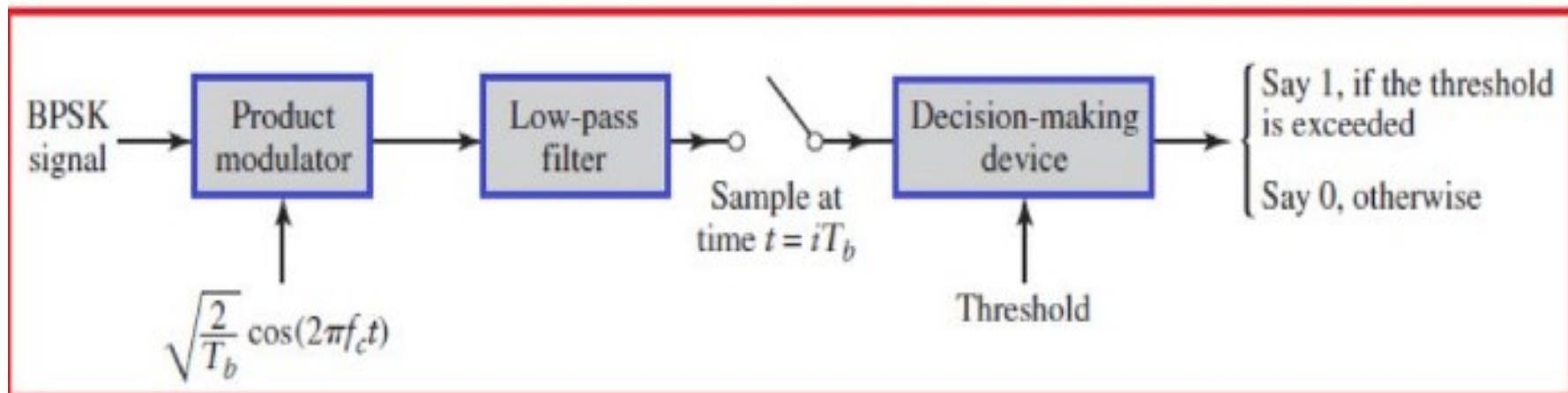
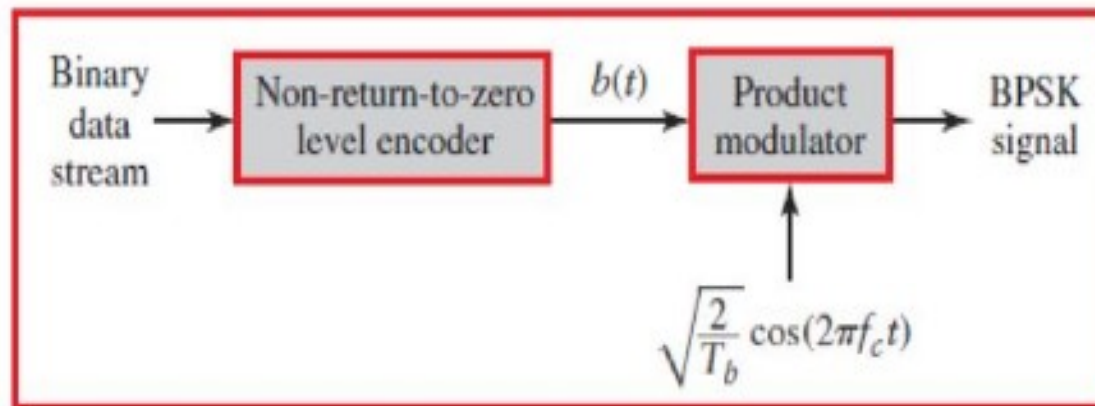
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## Coherent BPSK Transmitter and Receiver





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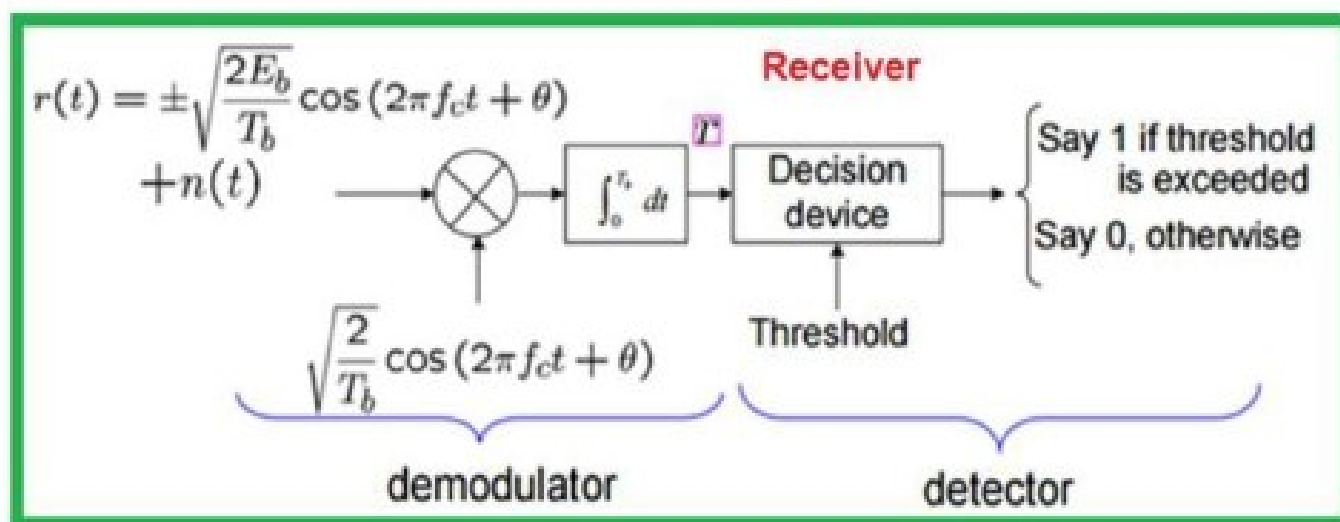
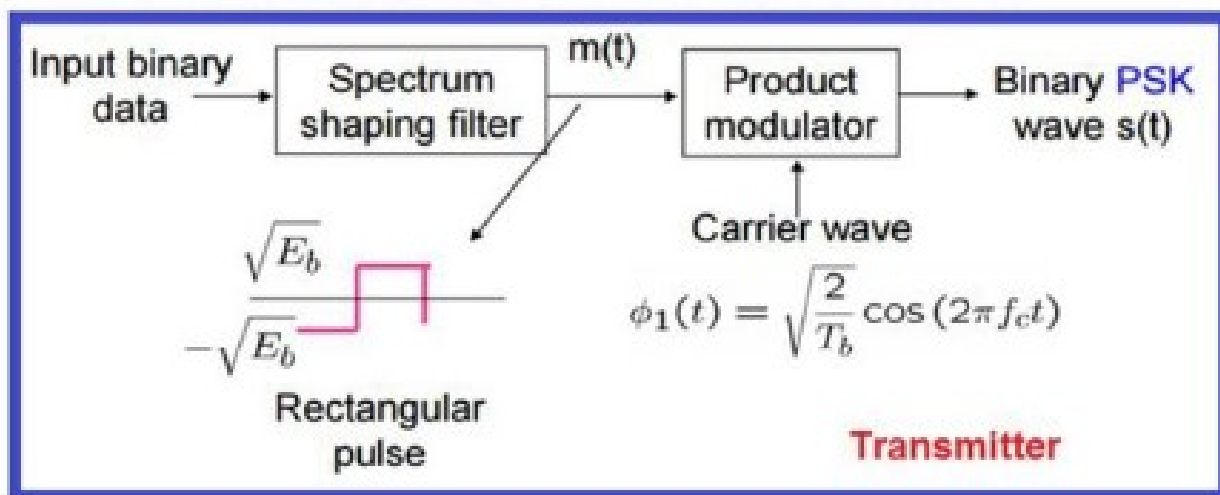
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## BPSK Transmitter and Receiver





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To generate a binary PSK wave, the input binary sequence in polar form with symbols 1 and 0 represented by constant amplitude levels of  $+\sqrt{E_b}$  and  $-\sqrt{E_b}$ , respectively.

- This binary wave and a sinusoidal carrier were  $\phi_1(t)$  (whose frequency  $f_c n_c/T_b$  for some fixed integer  $n_c$ ) are applied to a product modulator, as in Figure 4.2b.
- The carrier and the timing pulses used to generate the binary wave are usually extracted from a common master clock. The desired PSK wave is obtained at the modulator output.
- To detect the original binary sequence of 1s and 0s, we apply the noisy PSK wave  $x(t)$  (at the channel output) to a correlator, which is also supplied with a locally generated coherent reference signal  $\phi_1(t)$ , as in Figure 4.2b.



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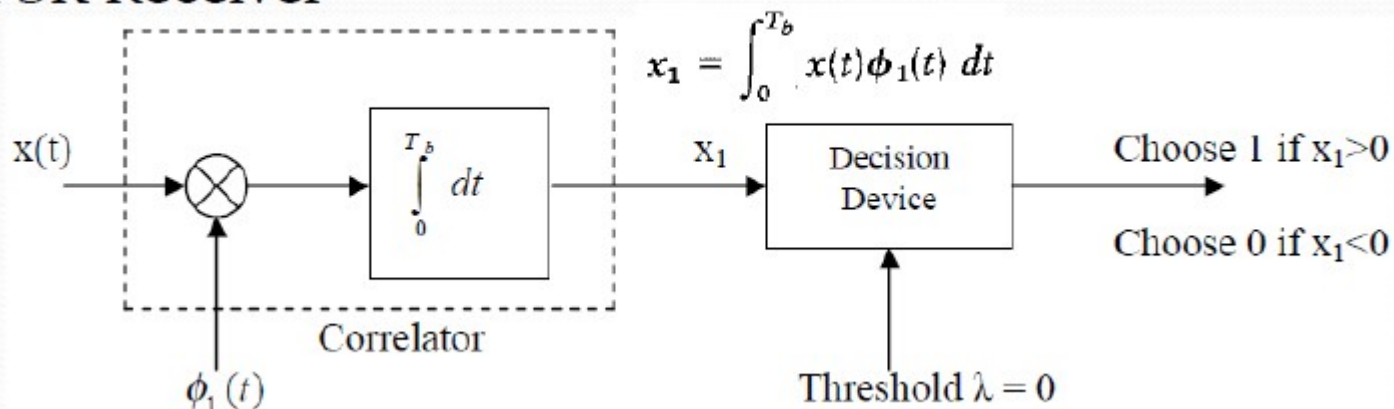
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- The correlator output,  $x_1$ , is compared with a threshold of zero volts.

If  $x_1 > 0$ , the receiver decides in favor of symbol 1.

If  $x_1 < 0$ , it decides in favor of symbol 0.

## BPSK Receiver





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A coherent binary PSK system is therefore characterized by having a signal space that is one-dimensional (i.e.,  $N = 1$ ) and with two message points (i.e.,  $M = 2$ ),

The coordinates of the message points equal

$$\begin{aligned} s_{11} &= \int_0^{T_b} s_1(t)\phi_1(t)dt & s_{21} &= \int_0^{T_b} s_2(t)\phi_1(t)dt \\ &= +\sqrt{E_b} & &= -\sqrt{E_b} \end{aligned}$$

- The message point corresponding to  $s_1(t)$  is located at  $s_{11} = +\sqrt{E_b}$ , and the message point corresponding to  $s_2(t)$  is located at  $s_{11} = -\sqrt{E_b}$ .
- We must partition the signal space of Fig. 4.1 into two regions:
  1. The set of points closest to the message point at  $+\sqrt{E_b}$
  2. The set of points closest to the message point at  $-\sqrt{E_b}$



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- This is accomplished by constructing the midpoint of the line joining these two message points, and then marking off the appropriate decision regions. In Figure 4.1 these decision regions are marked  $Z_1$  and  $Z_2$  according to the message point around which they are constructed.

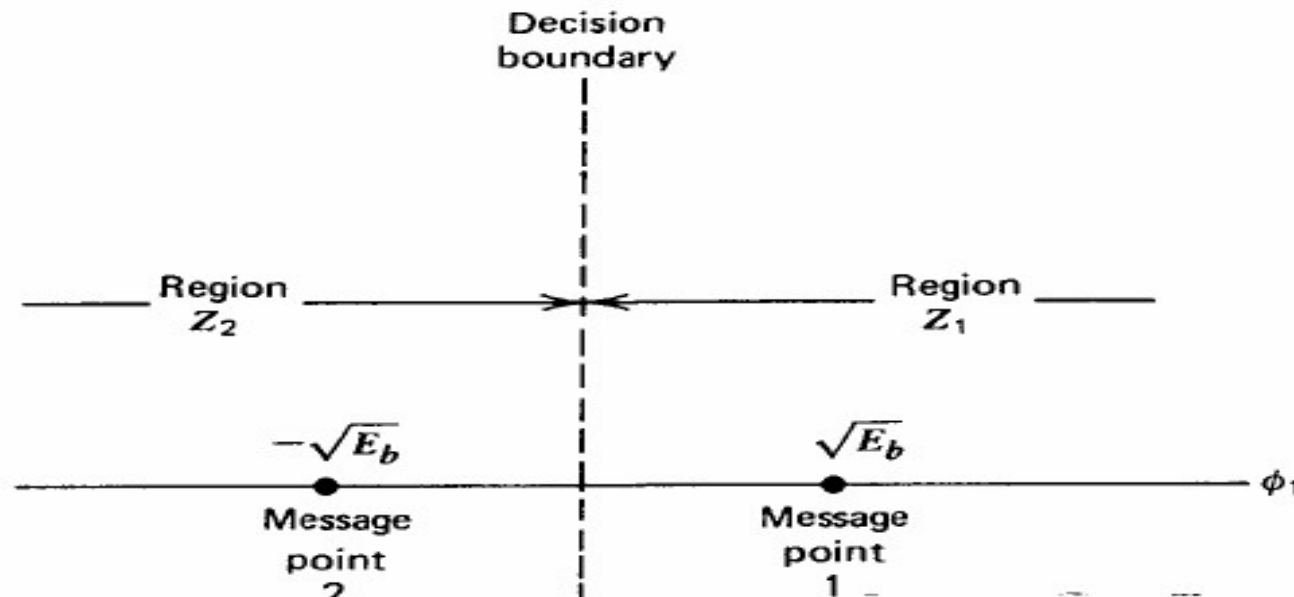


FIGURE 4.1 Signal space diagram for coherent binary PSK system



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## BPSK probability of error

$$s_{11} = \int_0^{T_b} s_1(t) \phi_1(t) dt = \sqrt{E_b}$$

$$s_{21} = \int_0^T s_2(t) \phi_1(t) dt = -\sqrt{E_b}$$

Desicion Regions

$$Z_1 : 0 < x_1 < \infty$$

$$Z_2 : -\infty < x_1 < 0$$

$$x_1 = \int_0^{T_b} x(t) \phi_1(t) dt$$

$$\begin{aligned} f_{x_1}(x_1|0) &= \frac{1}{\sqrt{\pi N_0}} \exp \left[ -\frac{1}{N_0} (x_1 - s_{21})^2 \right] \\ &= \frac{1}{\sqrt{\pi N_0}} \exp \left[ -\frac{1}{N_0} (x_1 + \sqrt{E_b})^2 \right] \end{aligned}$$



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- Probability of error when binary '0' is sent and received as '1'

$$P_{e0} = \frac{1}{\sqrt{\pi N_0}} \int_0^{\infty} \exp \left[ -\frac{(x_1 + \sqrt{E_b})^2}{N_0} \right] dx_1$$

$$\text{Put } Z = \frac{x_1 + \sqrt{E_b}}{\sqrt{N_0}}$$

$$P_{e0} = \frac{1}{\sqrt{\pi}} \int_{\sqrt{E_b/N_0}}^{\infty} \exp[(-Z)^2] dz$$

$$P_{e0} = \frac{1}{2} \operatorname{erfc} \sqrt{\frac{E_b}{N_0}}$$

- Similarly '1' sent and received '0'

$$P_{e1} = \frac{1}{2} \operatorname{erfc} \sqrt{\frac{E_b}{N_0}}$$

- Total  $P_e$  is average of  $P_{e0}$  and  $P_{e1}$

$$P_e = \frac{1}{2} \operatorname{erfc} \sqrt{\frac{E_b}{N_0}}$$



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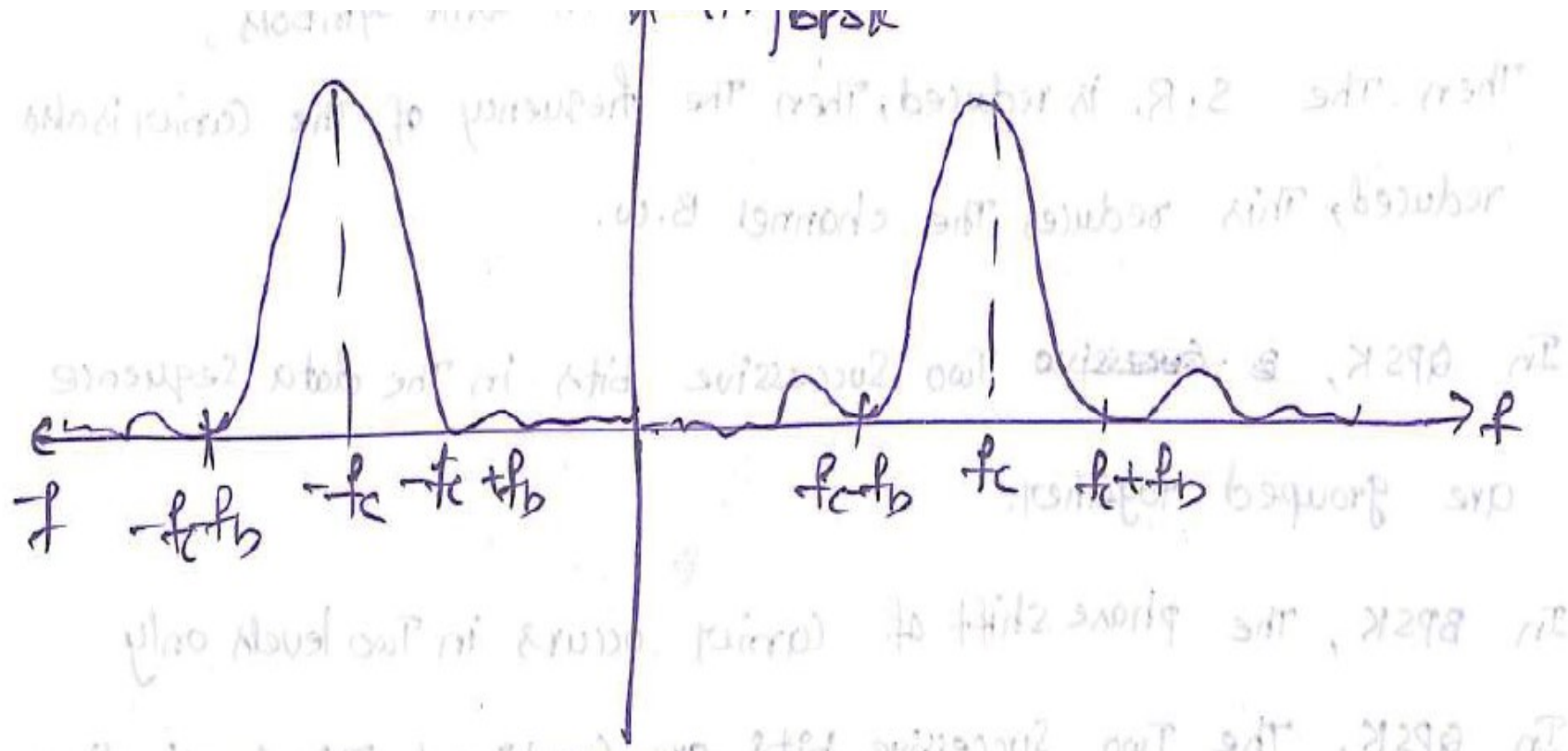
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- Probability of error calculation. In the case of equally likely ( $\Pr(m_0)=\Pr(m_1)$ ), we have

$$\begin{aligned} P_e &= \frac{1}{2} \operatorname{erfc} \left( \frac{d_{ik}}{2\sqrt{N_0}} \right) \\ &= \frac{1}{2} \operatorname{erfc} \left( \sqrt{\frac{E_b}{N_0}} \right) \end{aligned}$$

## Band width in BPSK



$$Bw = f_c + f_b - (-f_c + f_b) = 2f_b$$



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# Quadrature Phase-Shift Keying (QPSK)

QPSK → Quadrature Phase Shift Keying

- **Four** different phase states in **one** symbol period
- **Two** bits of information in each symbol

Phase:  $0$   $\pi/2$   $\pi$   $3\pi/2$  → possible phase values

Symbol: 00 01 11 10

**Odd and even bits** are separated in data sequence

Odd bits are in one channel(In-phase)

Even bits are in Quadrature Channel



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$$s_i(t) = \sqrt{\frac{2E}{T}} \cos \left[ 2\pi f_c t + (2i - 1) \frac{\pi}{4} \right]; \quad 0 \leq t < T$$

$i = 1, 2, 3, \text{ and } 4$

- $T$  is symbol duration
- $E$  is signal energy per symbol
- There are 4 symbols for  $i = 1, 2, 3, \text{ and } 4$
- Data sequence    10 11 00 10 00
- Odd bits 11010
- Even Bits 01000



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$$\begin{aligned}s_i(t) &= \sqrt{E} \cos\left[(2i-1)\frac{\pi}{4}\right] \sqrt{\frac{2}{T}} \cos(2\pi f_c t) - \sqrt{E} \sin\left[(2i-1)\frac{\pi}{4}\right] \sqrt{\frac{2}{T}} \sin(2\pi f_c t) \\ &= \sqrt{E} \cos\left[(2i-1)\frac{\pi}{4}\right] \phi_1(t) - \sqrt{E} \sin\left[(2i-1)\frac{\pi}{4}\right] \phi_2(t); \quad 0 \leq t < T\end{aligned}$$

$$\phi_1(t) = \sqrt{\frac{2}{T}} \cos(2\pi f_c t), \quad 0 \leq t \leq T$$

$$\phi_2(t) = \sqrt{\frac{2}{T}} \sin(2\pi f_c t), \quad 0 \leq t \leq T$$

- Which we can write in vector format as

$$\mathbf{s}_i = \begin{bmatrix} \sqrt{E} \cos(2i-1)\frac{\pi}{4} \\ -\sqrt{E} \sin(2i-1)\frac{\pi}{4} \end{bmatrix} \quad i = 1, 2, 3, \text{ and } 4$$



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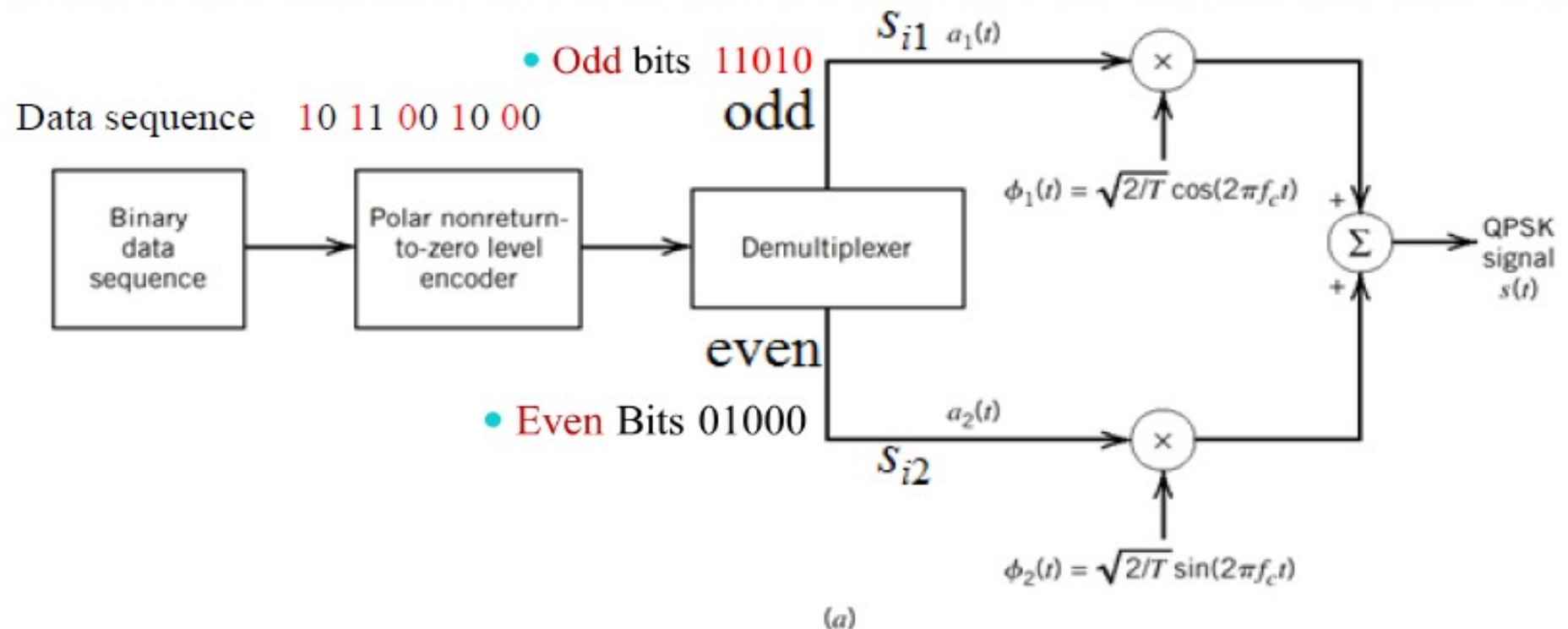
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- $s_i(t) = s_{i1}\phi_1(t) + s_{i2}\phi_2(t)$



- Block diagrams of QPSK transmitter

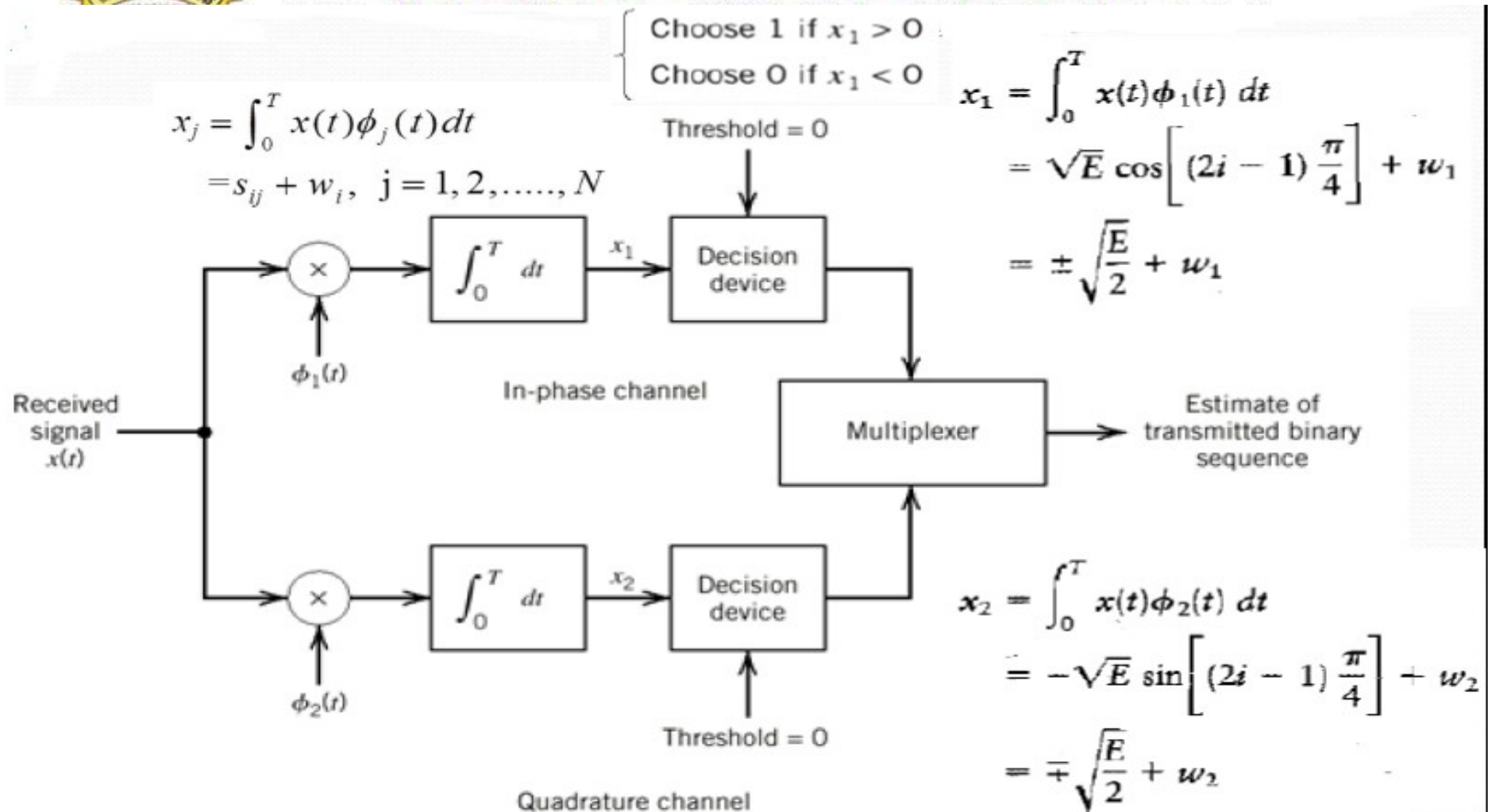


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- Block diagram of Coherent<sup>(b)</sup> QPSK receiver.



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$i$	Input Dibit	Phase of QPSK signaling	Coordinate of Message point	
			$S_{i1}$	$S_{i2}$
1	10	$\pi/4$	$\sqrt{E/2}$	$-\sqrt{E/2}$
2	00	$3\pi/4$	$-\sqrt{E/2}$	$-\sqrt{E/2}$
3	01	$5\pi/4$	$-\sqrt{E/2}$	$\sqrt{E/2}$
4	11	$7\pi/4$	$\sqrt{E/2}$	$\sqrt{E/2}$



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$$VQPSK(t) = b_o(t) \cdot \sqrt{P_s} \cos 2\pi f_c t + b_e(t) \cdot \sqrt{P_s} \sin 2\pi f_c t$$

1(+v)	0(-v) → $\pi/4$
0(-v)	0(-v) → $3\pi/4$
0(-v)	1(+v) → $5\pi/4$
1(+v)	1(+v) → $7\pi/4$

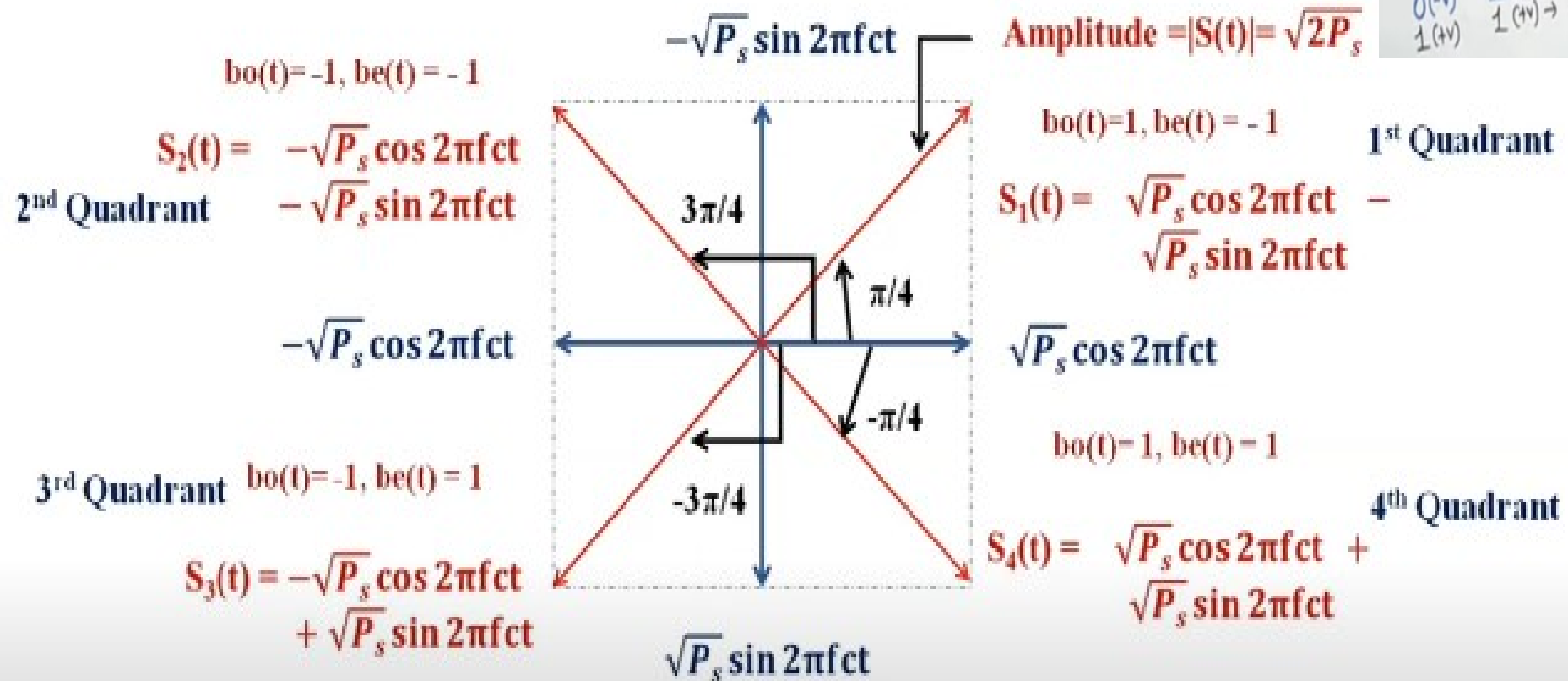


Fig. 3: Phasor Diagram of  $\pi/4$ -QPSK Signal



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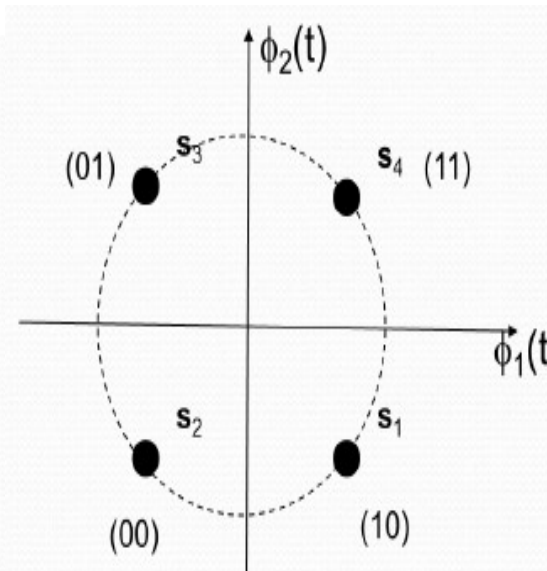
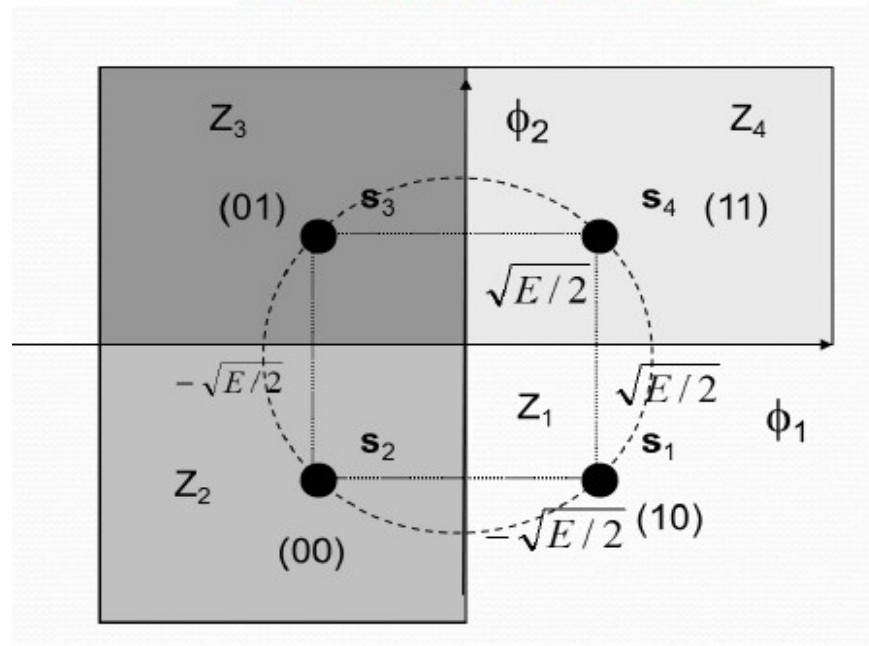
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## QPSK Constellation



$s_{i1}$	$s_{i2}$
$\sqrt{E/2}$	$-\sqrt{E/2}$
$-\sqrt{E/2}$	$-\sqrt{E/2}$
$-\sqrt{E/2}$	$\sqrt{E/2}$
$\sqrt{E/2}$	$\sqrt{E/2}$



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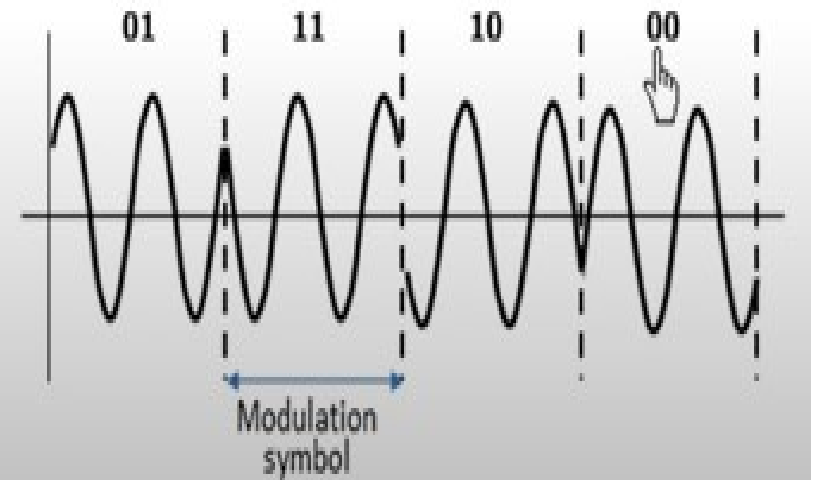
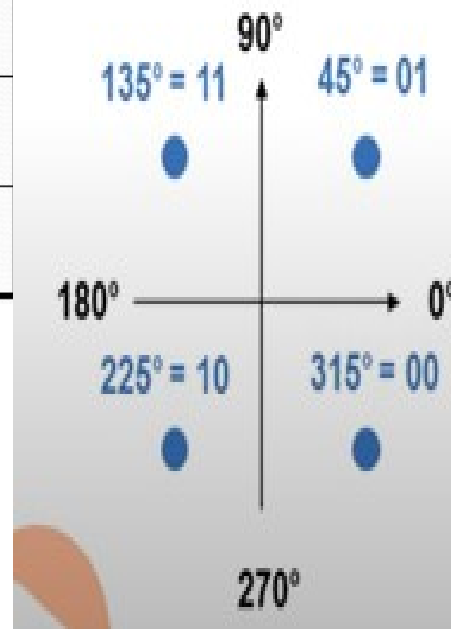
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10	$\pi/4$
00	$3\pi/4$
01	$5\pi/4$
11	$7\pi/4$





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## Quadrature Phase Shift Keying





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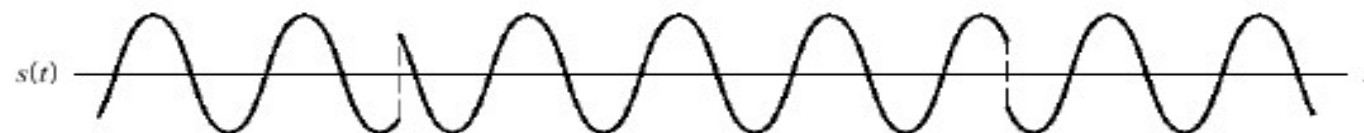
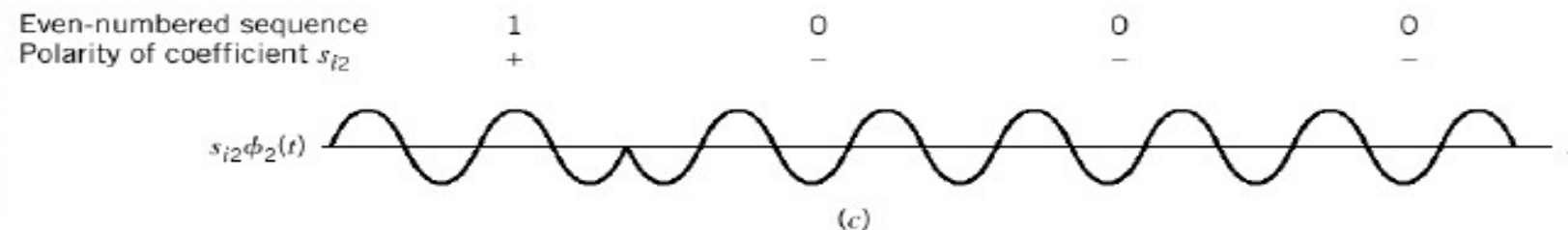
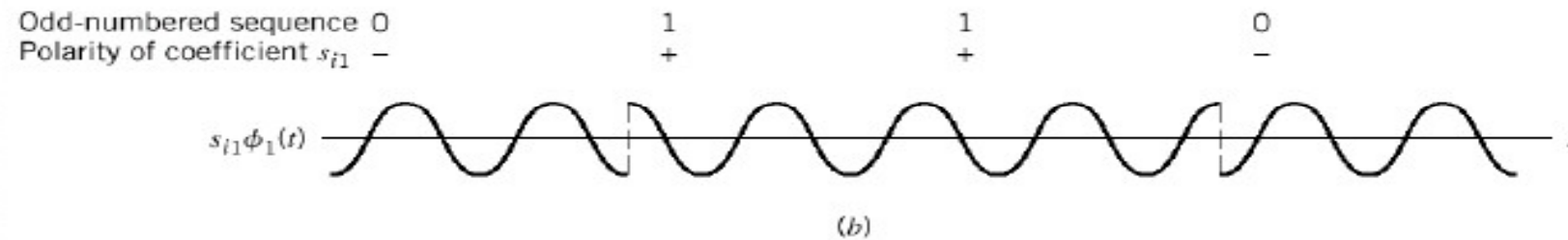
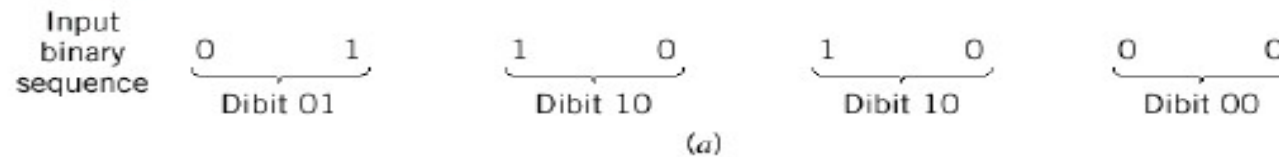
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## QPSK signals





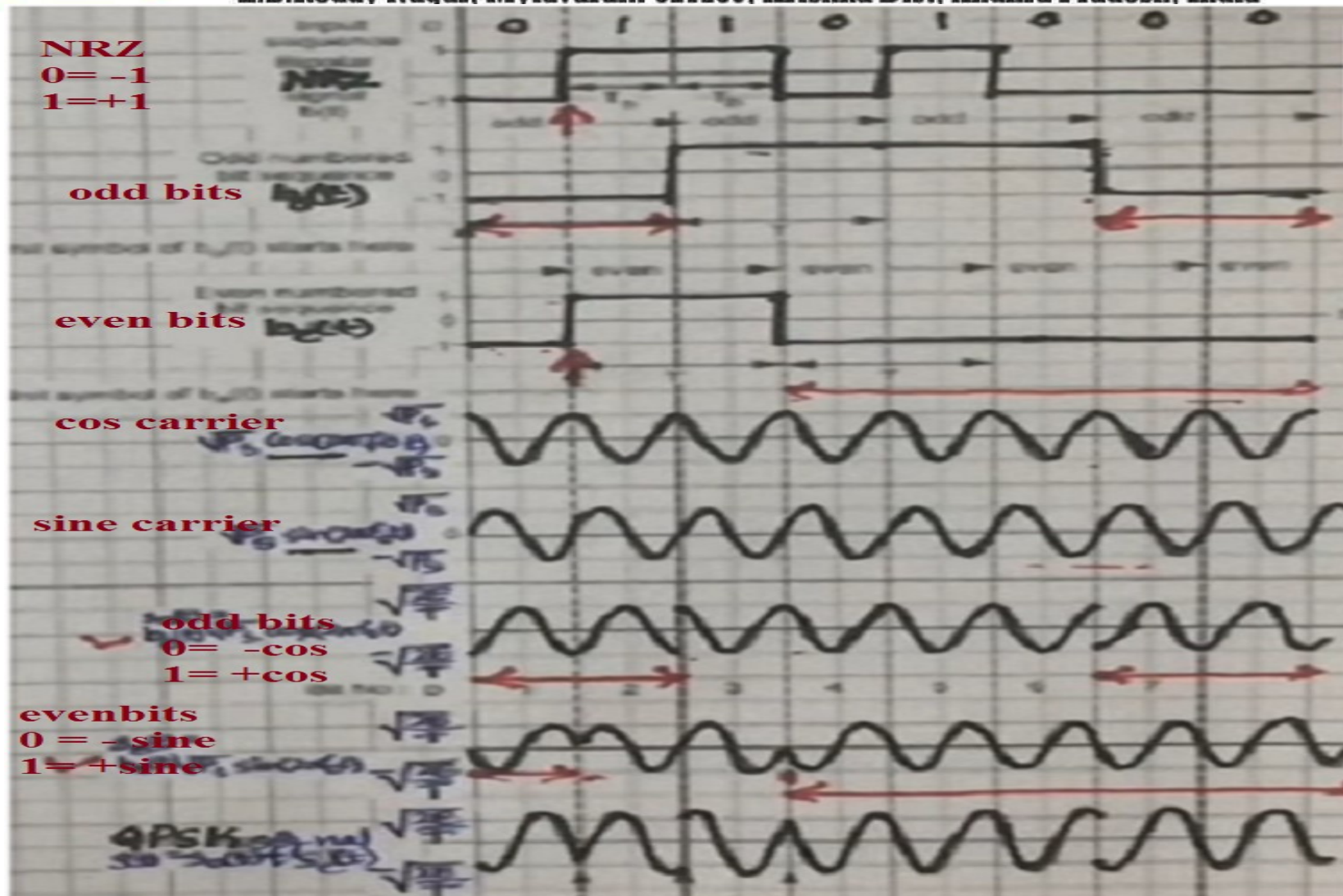
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- Bandwidth of BPSK signal,  $BW = 2f_b$ .

where  $f_b$  is input bit rate and  $T_b = \frac{1}{f_b}$ , is one bit duration.

- In QPSK, two waveforms forms the baseband signal, In-phase signal  $b_o(t)$  and Quadrature signal  $b_e(t)$ .
- One bit period for these signal is  $T_s = 2 T_b$ .
- Bandwidth of QPSK signal is

$$BW = \frac{2}{T_s} = \frac{2}{2T_b} = \frac{1}{T_b} = f_b$$



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• we can make the following conclusions:

1. The carrier phase changes by  $\pm 180^\circ$  whenever **both the in-phase and the quadrature components** of the QPSK signal change sign (01 to 10)
2. The carrier phase changes by  $\pm 90^\circ$  degrees whenever the **in-phase or quadrature component** changes sign (10 to 00 – in-phase changes, quadrature doesn't changes)
3. The carrier phase is unchanged when neither the in-phase nor the quadrature component change sign. (10 and then 10 again).

**Conclusion:** Situation 1 is of concern when the QPSK signal is filtered during transmission because *the 180 or also 90 degrees shifts in carrier phase might result in changes in amplitude* (envelope of QPSK), which will cause symbol errors



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- Whenever both bits are changed simultaneously,  $180^\circ$  phase-shift occurs.
- At  $180^\circ$  phase-shift, the amplitude of the transmitted signal changes very rapidly causing amplitude fluctuation.
- This signal may be distorted when is passed through the filter or nonlinear amplifier.



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## Conclusions

- QPSK is capable of transmitting data twice as faster as BPSK with the same energy per bit.
- QPSK has *half of the bandwidth* of BPSK.
- Since one symbol of QPSK consists of two bits, we have  $E = 2E_b$ .
- Symbol duration  $T = 2T_b$ .
- Used in *Wireless Communications*



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## QPSK Probability of error

- We can treat QPSK as the combination of 2 independent BPSK over the interval  $T=2T_b$
- since the first bit is transmitted by  $\phi_1$  and the second bit is transmitted by  $\phi_2$ .
- Probability of error for each channel is given by

$$P' = \frac{1}{2} \operatorname{erfc} \left( \frac{d_{12}}{2\sqrt{N_0}} \right) = \frac{1}{2} \operatorname{erfc} \left( \sqrt{\frac{E}{2N_0}} \right)$$



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- If symbol is to be received correctly both bits must be received correctly.
- Hence, the average probability of correct decision is given by  $P_c = (1 - P')^2$
- Which gives the probability of errors equal to

$$P_e = 1 - P_C = \operatorname{erfc}\left(\sqrt{\frac{E}{2N_0}}\right) - \frac{1}{4}\operatorname{erfc}^2\left(\sqrt{\frac{E}{2N_0}}\right)$$
$$\approx \operatorname{erfc}\left(\sqrt{\frac{E}{2N_0}}\right)$$



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- Since one symbol of QPSK consists of two bits, we have  $E = 2E_b$ .

$$Pe(\text{per symbol}) \approx \text{erfc}\left(\sqrt{\frac{E_b}{N_0}}\right)$$

- The above probability is the error probability per symbol. The avg. probability of error per bit

$$Pe(\text{per bit}) = \frac{1}{2} Pe(\text{per symbol}) \approx \frac{1}{2} \text{erfc}\left(\sqrt{\frac{E_b}{N_0}}\right)$$

- Which is exactly the same as BPSK .



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## M-array PSK

- At a moment, there are M possible symbol values being sent for M different phase values,

$$\theta_i = 2(i-1)\pi / M$$

$$s_i(t) = \sqrt{\frac{2E}{T}} \cos\left(2\pi f_c t + \frac{2\pi}{M}(i-1)\right), \quad i = 1, 2, \dots, M$$



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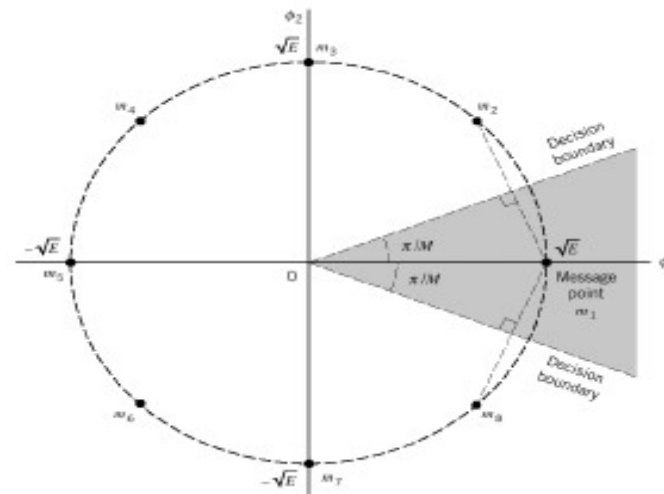
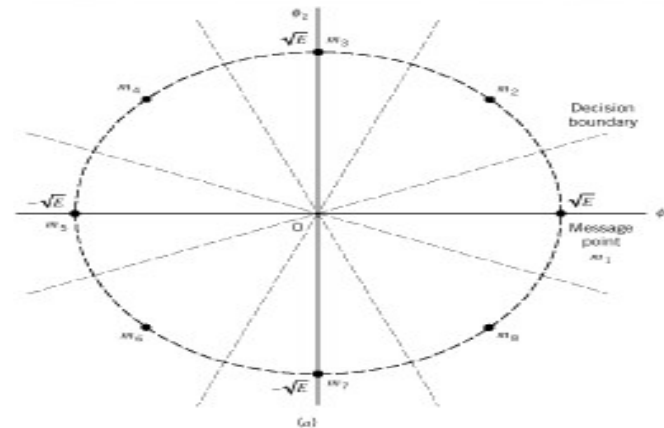
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## M-array PSK

- Signal-space diagram for octaphase-shift keying (i.e.,  $M = 8$ ). The decision boundaries are shown as dashed lines.
- Signal-space diagram illustrating the application of the union bound for octaphase-shift keying.





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- Bandwidth efficiency:
  - We only consider the bandwidth of the main lobe (or null-to-null bandwidth)

$$B = \frac{2}{T} = \frac{2}{T_b \log_2 M} = \frac{2R_b}{\log_2 M}$$

- Bandwidth efficiency of M-ary PSK is given by

$$\rho = \frac{R_b}{B} = \frac{R_b}{2R_b} \log_2 M = 0.5 \log_2 M$$



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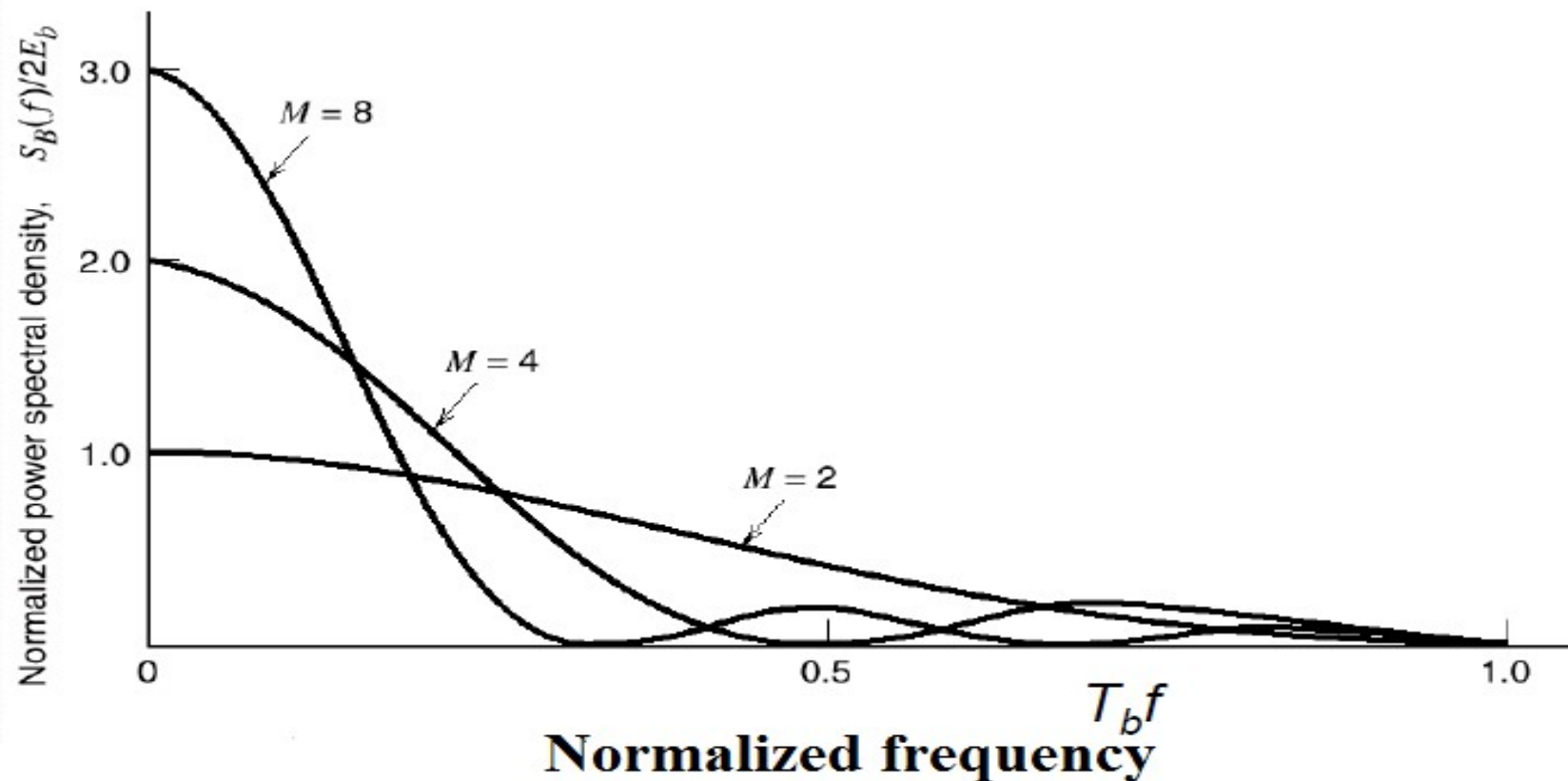
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- Power spectra of  $M$ -ary PSK signals for  $M = 2, 4, 8$ .





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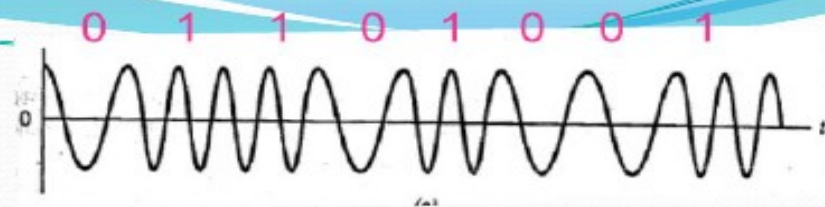
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## Binary FSK



- Transmitted signals are

$$s_i(t) = \begin{cases} \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_i t), & 0 < t \leq T_b \\ 0, & \text{elsewhere} \end{cases}$$

- Where

$$f_i = \frac{n_c + i}{T_b}; \quad i = 1, 2$$

- Two binary values represented by two different frequencies which are orthogonal to each other
- The signal points  $S_1(t)$  and  $S_2(t)$  can be expressed as:
- $S_i(t) = s_{i1}\phi_1(t) + s_{i2}\phi_2(t)$  for  $i=1, 2$   $0 \leq t \leq T$

where  $\phi_1(t), \phi_2(t)$  orthonormal basis functions



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- Here two orthonormal basis functions are required to represent  $s_1(t)$  and  $s_2(t)$ . They are written as for  $i=1,2$

$$\phi_i(t) = \begin{cases} \sqrt{\frac{2}{T_b}} \cos(2\pi f_i t), & 0 < t \leq T_b \\ 0, & \text{elsewhere} \end{cases} \quad \begin{aligned} \phi_1(t) &= \sqrt{\frac{2}{T_b}} \cos(2\pi f_1 t) \\ \phi_2(t) &= \sqrt{\frac{2}{T_b}} \cos(2\pi f_2 t) \end{aligned}$$

- As a result, the signal vectors are
- $S_i(t) = s_{i1}\phi_1(t) + s_{i2}\phi_2(t)$  for  $i=1,2$
- $S_1(t)$  represented symbol "1".
- $S_2(t)$  represented symbol "0".

$$s_1(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_1 t)$$

$$s_1(t) = \sqrt{E_b} \phi_1(t)$$

$$s_2(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_2 t)$$

$$s_2(t) = \sqrt{E_b} \phi_2(t)$$

$$s_1 = \begin{bmatrix} \sqrt{E_b} \\ 0 \end{bmatrix} \quad \text{and} \quad s_2 = \begin{bmatrix} 0 \\ \sqrt{E_b} \end{bmatrix}$$



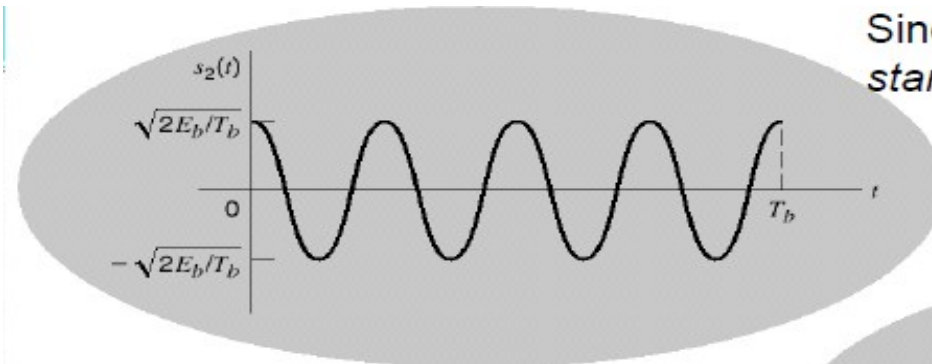
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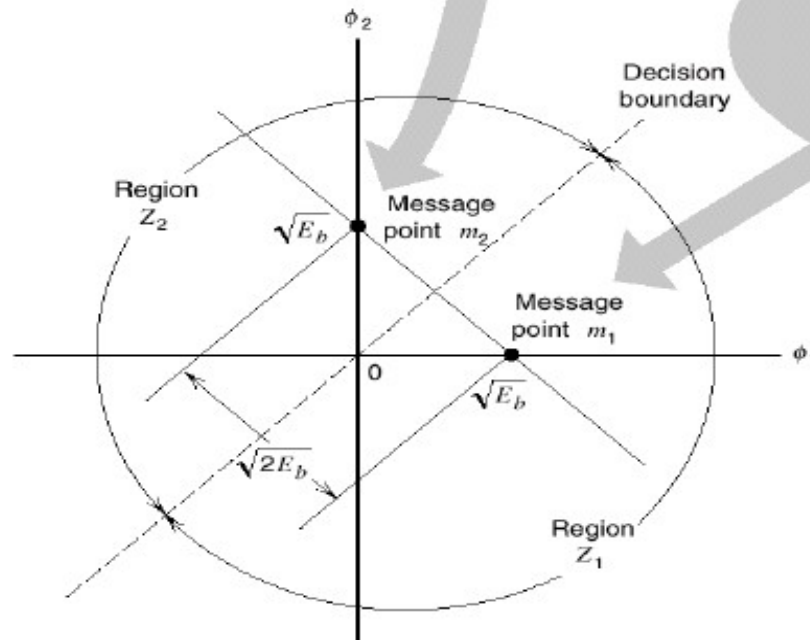
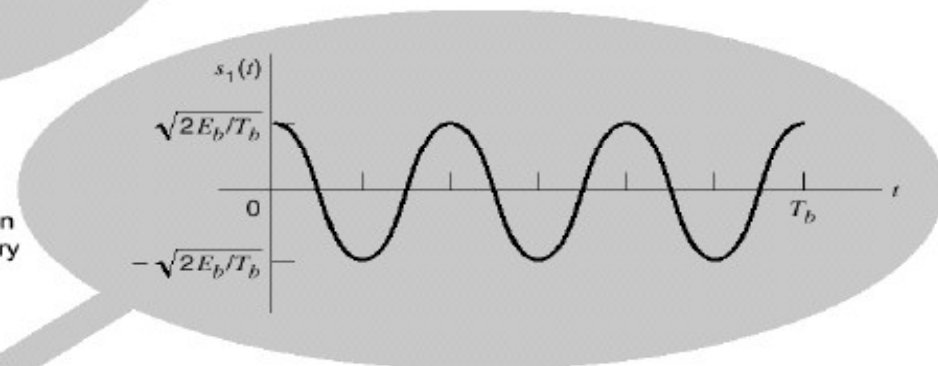
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Since  $f_i$  is multiple of  $1/T_b$  the wave always starts from and ends at the same point.



With this multiple- $(1/T_b)$  restriction, it becomes “continuous-phase” in every inter-bit transition. Such kind of forced “continuous-phase” signals, known as **Sunde's FSK**, surely belongs to the general continuous-phase FSK (CPFSK) family.



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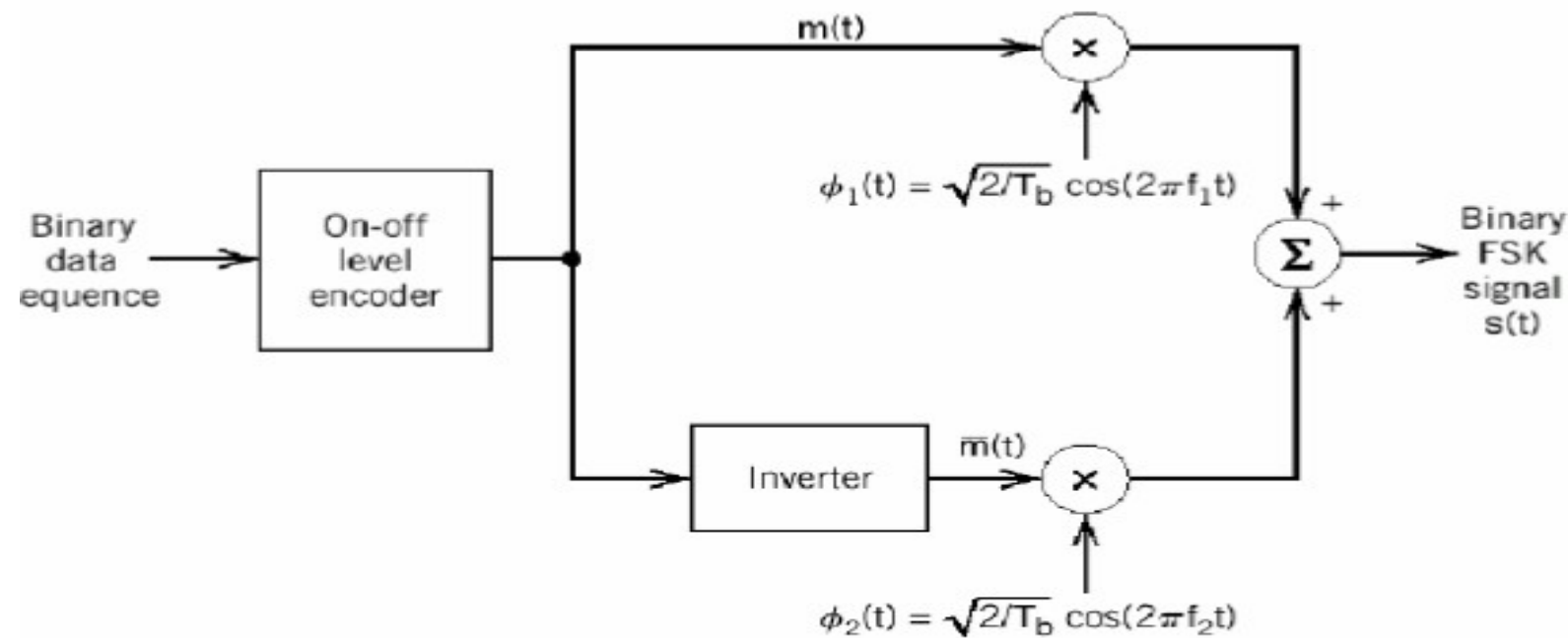
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## Binary FSK Transmitter

$f_i$ : transmitted frequency with separation  $\Delta f = f_1 - f_0$   
 $\Delta f$  is selected so that  $s_1(t)$  and  $s_2(t)$  are orthogonal to each other

$$\int_0^{T_b} s_1(t) s_2(t) dt = 0$$




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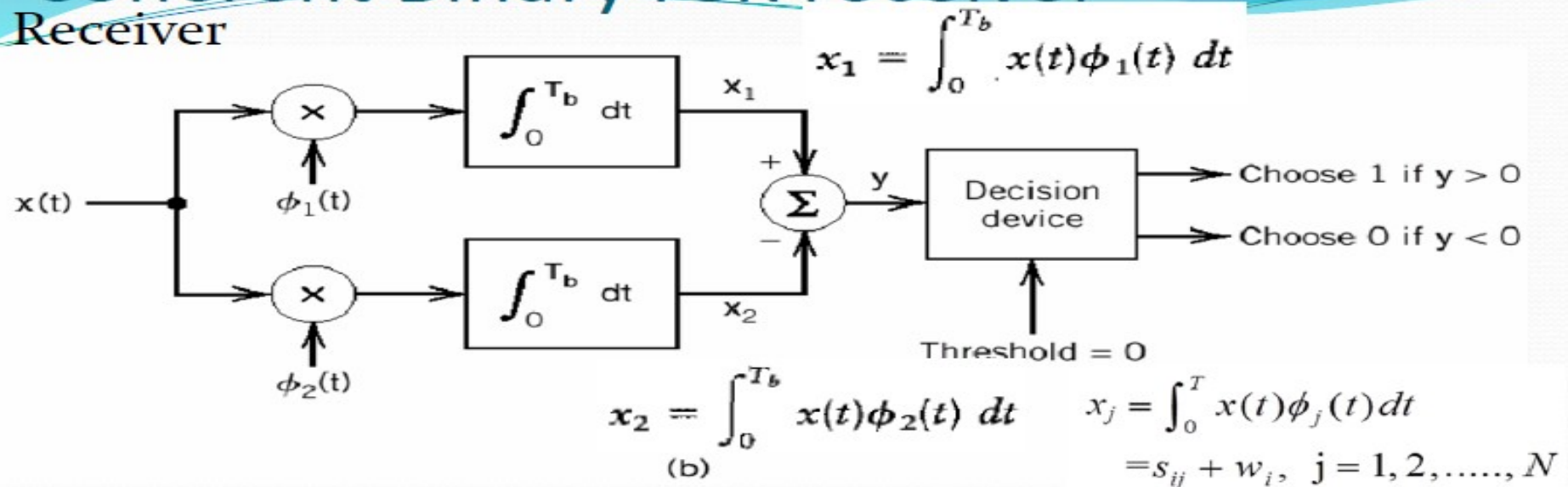
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## Coherent Binary FSK receiver

Receiver



The output  $y = x_1 - x_2$ , The decision boundary is characterized by the line with  $x_1 - x_2 = 0$

If  $x_1 - x_2 > 0$  (the received signal point lies in region  $Z_1$ ), the decision device makes a decision of 1)

If  $x_1 - x_2 < 0$  (the received signal point lies in region  $Z_2$ ), the decision device makes a decision of 0.)



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- If the signal ( $s_1$ ) was transmitted, the outputs  $x_1$  and  $x_2$  of the correlators can be expressed as:

$$x_1 = \int_0^T \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_1 t) \sqrt{\frac{2}{T_b}} \cos(2\pi f_1 t) dt = \sqrt{E_b}$$

$$x_2 = \int_0^T \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_1 t) \sqrt{\frac{2}{T_b}} \cos(2\pi f_2 t) dt = 0.$$

- If the signal ( $s_2$ ) was transmitted, the outputs of the correlators can be expressed as:

$$x_1 = \int_0^T \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_2 t) \sqrt{\frac{2}{T_b}} \cos(2\pi f_1 t) dt = 0$$

$$x_2 = \int_0^T \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_2 t) \sqrt{\frac{2}{T_b}} \cos(2\pi f_2 t) dt = \sqrt{E_b}.$$



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## BFSK Probability of error

Gaussian random variable  $Y$  whose sample value  $y$  is equal to the difference between  $x_1$  and  $x_2$ ; i.e.,  $y = x_1 - x_2$

The mean value of the random variable  $Y$  depends on which binary symbol was transmitted.

Given that **symbol 1 was sent**, the Gaussian random variables  $X_1$  and  $X_2$ , whose sample values are denoted by  $x_1$  and  $x_2$ , have mean values equal to  $\sqrt{E_b}$  and zero, respectively.

Correspondingly, the conditional mean of the random variable  $Y$  given that symbol 1 was sent is

$$\begin{aligned}\mathbb{E}[Y|1] &= \mathbb{E}[X_1|1] - \mathbb{E}[X_2|1] \\ &= +\sqrt{E_b}\end{aligned}$$



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- Given that symbol 0 was sent, the Gaussian random variables  $X_1$  and  $X_2$ , whose sample values are denoted by  $x_1$  and  $x_2$ , have mean values equal to zero and  $\sqrt{E_b}$ , respectively. Correspondingly, the conditional mean of the random variable  $Y$  given that symbol 0 was sent is

$$\mathbb{E}[Y|0] = \mathbb{E}[X_1|0] - \mathbb{E}[X_2|0] = -\sqrt{E_b}$$

- The variance of the random variable  $Y$  is independent of which binary symbol was sent.
- Since the random variables  $X_1$  and  $X_2$  are statistically independent, each with a variance equal to  $N_0/2$ , it follows that

$$\text{var}[Y] = \text{var}[X_1] + \text{var}[X_2] = N_0$$



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- Suppose we know that symbol 0 was sent. The conditional probability density function of the random variable Y is then given by

$$f_Y(y|0) = \frac{1}{\sqrt{2\pi N_0}} \exp\left[-\frac{(y + \sqrt{E_b})^2}{2N_0}\right]$$

- Since the condition  $x_1 > x_2$  or, equivalently,  $y > 0$  corresponds to the receiver making a decision in favor of symbol 1, we deduce that the conditional probability of error given that symbol 0 was sent is

$$\begin{aligned} p_{10} &= \mathbb{P}(y > 0 | \text{symbol 0 was sent}) = \int_0^{\infty} f_Y(y|0) dy \\ &= \frac{1}{\sqrt{2\pi N_0}} \int_0^{\infty} \exp\left[-\frac{(y + \sqrt{E_b})^2}{2N_0}\right] dy \end{aligned}$$

- Let  $\frac{y + \sqrt{E_b}}{\sqrt{2N_0}} = z$  then  $p_{10} = \frac{1}{\sqrt{\pi}} \int_{\sqrt{E_b/2N_0}}^{\infty} \exp\left(-\frac{z^2}{2}\right) dz$



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- Similarly, we may show the  $p_{01}$ , the conditional probability of error given that symbol 1 was sent.
- Accordingly, averaging  $p_{10}$  and  $p_{01}$  and assuming equiprobable symbols, we find that the average probability of bit error or, equivalently, the BER for binary FSK using coherent detection is

$$P_e = \frac{1}{2} \operatorname{erfc} \left( \sqrt{\frac{E_b}{2N_0}} \right)$$



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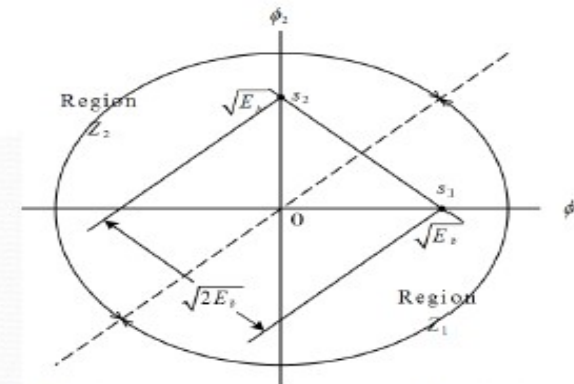
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## BFSK



- Euclidean distance is  $d_{12} = \sqrt{2E_b}$
- In case of  $P_r(0)=P_r(1)$ , the probability of error is given by

$$P_e = \frac{1}{2} \operatorname{erfc} \left( \frac{d_{ik}}{2\sqrt{N_0}} \right) \quad P_e = \frac{1}{2} \operatorname{erfc} \left( \sqrt{\frac{E_b}{2N_0}} \right)$$

- *Probability of error  $P_e$  of BFSK system is more than the BPSK system.*
- *We observe that at a given value of  $P_e$ , the BFSK system requires twice as much power as that BPSK system.*



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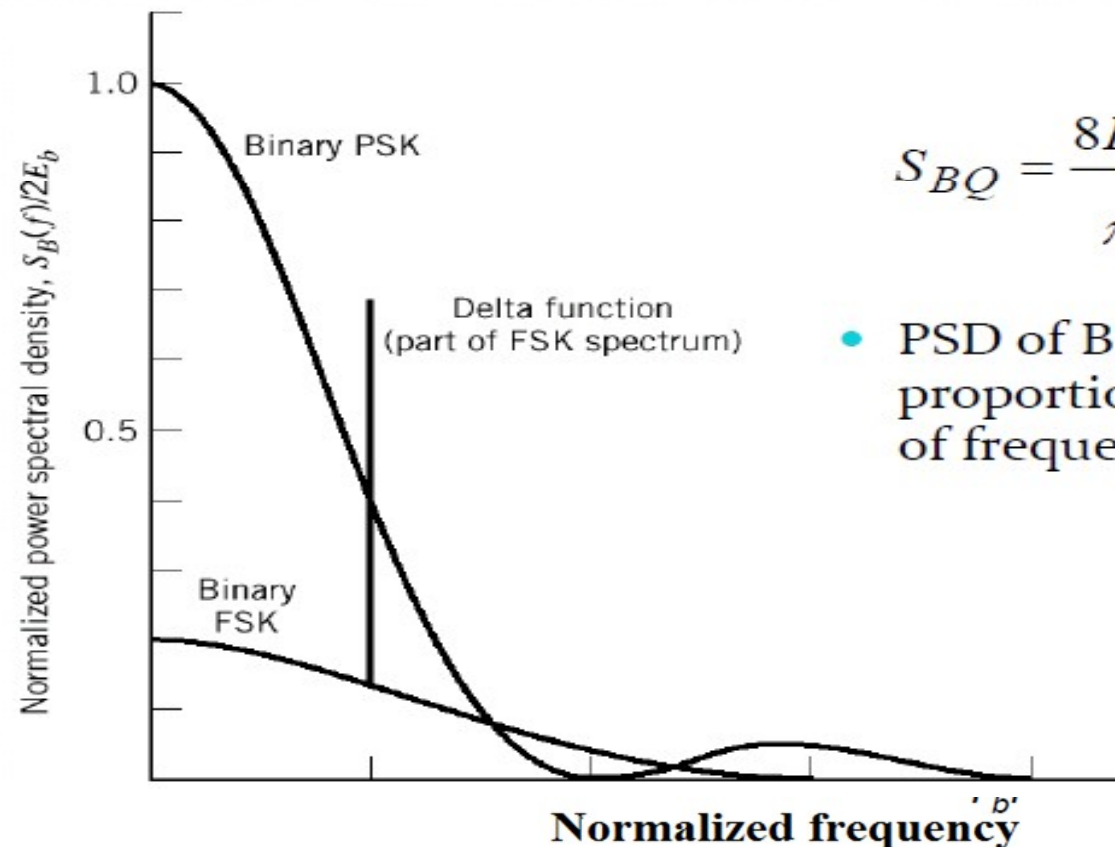
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## Power Spectral density of BFSK

- Finally, we obtain

$$S_B(f) = S_{BI}(f) + S_{BQ}(f)$$



$$S_{BQ} = \frac{8E_b T_b \cos^2(\pi T_b f)}{\pi^2 (4T_b^2 f^2 - 1)^2}$$

- PSD of BFSK is inversely proportional to fourth power of frequency



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## Differential PSK (DPSK)

- **DPSK** can be viewed as the **non-coherent** version of PSK
- Phase difference between **two successive bit intervals** is independent of theta
- Phase synchronization is eliminated using **differential encoding**
- Differential PSK
  - Instead of finding the phase of the signal on the interval  $0 < t \leq T_b$ . This receiver determines the **phase difference** between **adjacent time intervals**.
  - If “1” is sent, the **phase** will remain **the same**
  - If “0” is sent, the **phase** will **change 180 degree**.



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The relationship between the binary sequence and its differentially encoded version is shown in table for a assumed data sequence 0 0 1 0 0 1 0 0 1 1 1.

Binary Data		0	0	1	0	0	1	0	0	1	1
Differentially Encoded Data	1	0	1	1	0	1	1	0	1	1	1
Phase of DPSK	0	$\pi$	0	0	$\pi$	0	0	$\pi$	0	0	0
Shifted Differentially encoded Data $d_{k-1}$		1	0	1	1	0	1	1	0	1	1
Phase of shifted Data		0	$\pi$	0	0	$\pi$	0	0	$\pi$	0	0
Phase Comparision Output		-	-	+	-	-	+	-	-	+	+
Detected Binary Seq.		0	0	1	0	0	1	0	0	1	1



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- Or we have binary “1”

$$s_1(t) = \begin{cases} \sqrt{\frac{E_b}{2T_b}} \cos(2\pi f_c t); & 0 < t \leq T_b \\ \sqrt{\frac{E_b}{2T_b}} \cos(2\pi f_c t); & T_b < t \leq 2T_b \end{cases}$$

- And binary “0”

$$s_2(t) = \begin{cases} \sqrt{\frac{E_b}{2T_b}} \cos(2\pi f_c t); & 0 < t \leq T_b \\ \sqrt{\frac{E_b}{2T_b}} \cos(2\pi f_c t + \pi); & T_b < t \leq 2T_b \end{cases}$$



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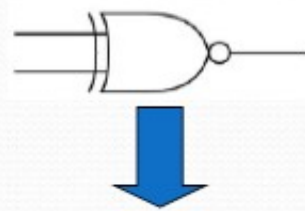
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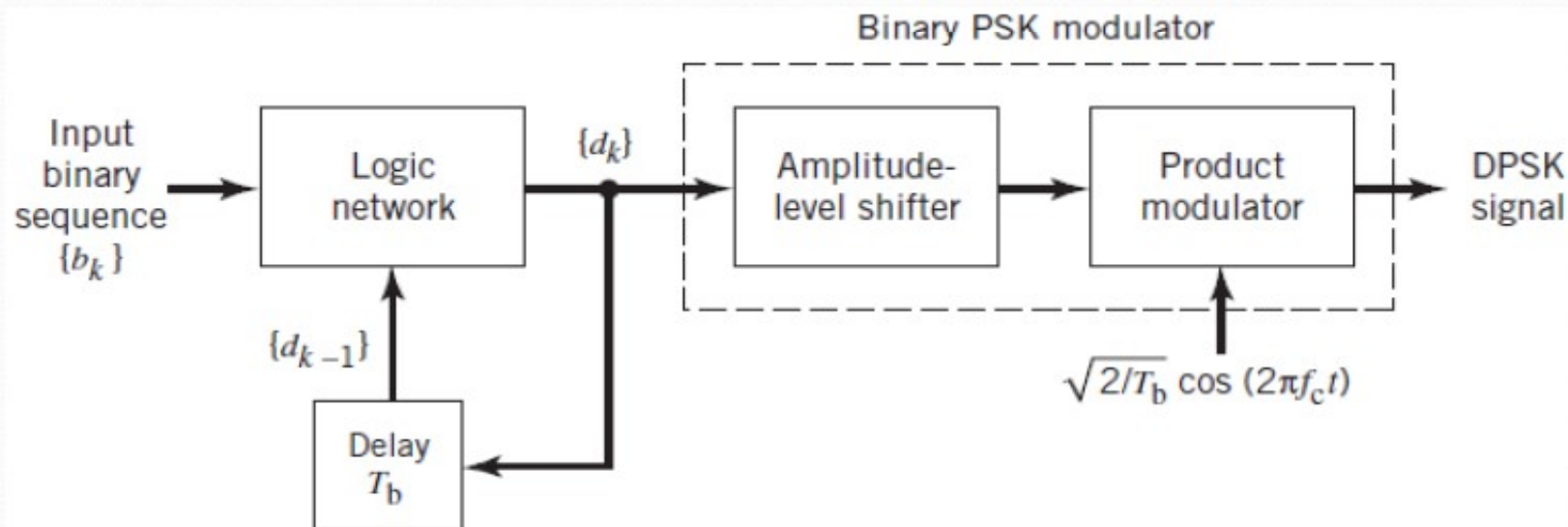
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## DPSK: Transmitter



$$d_k = b_k d_{k-1} \oplus \bar{b}_k \bar{d}_{k-1}$$



Block diagram of a DPSK transmitter.

- Exclusive-NOR logic



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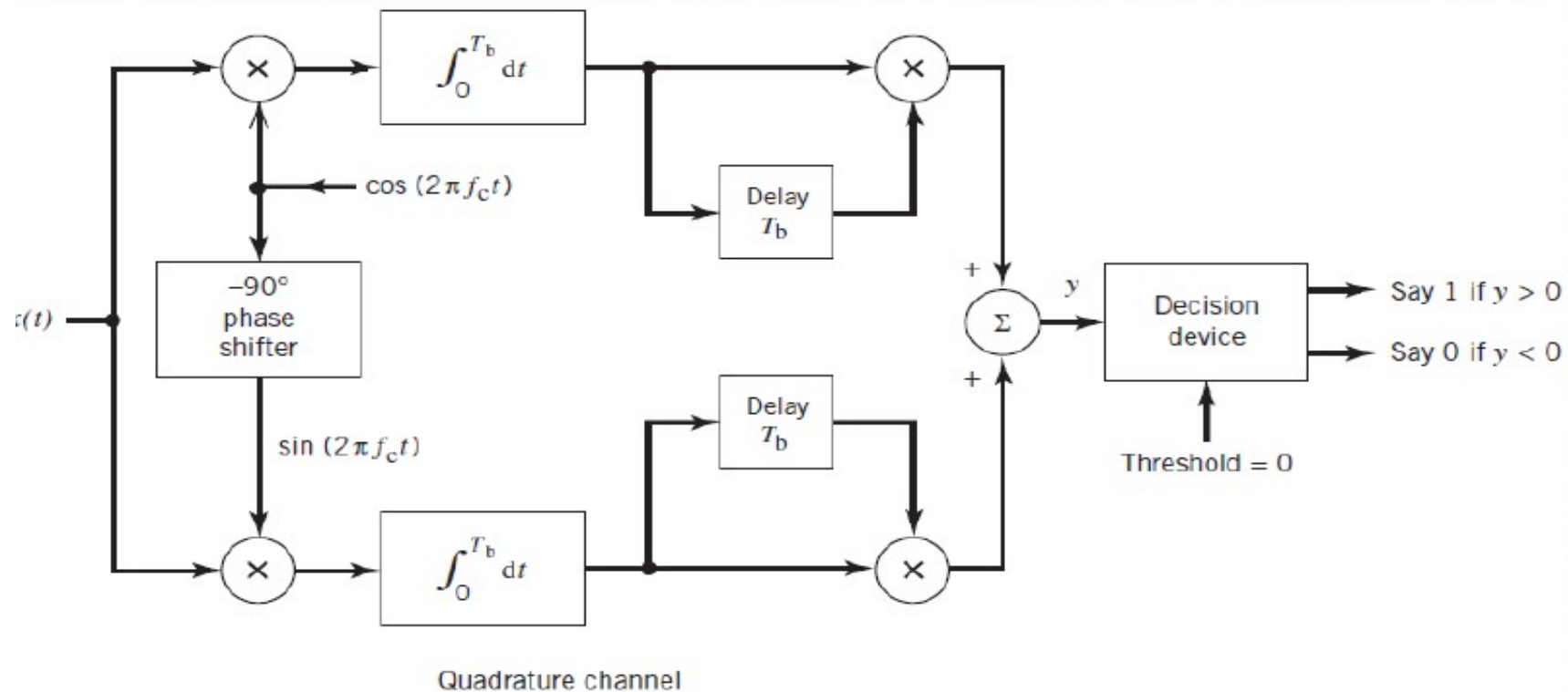
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## DPSK: Receiver

Phase

+ + - + + - + - - -



Block diagram of a DPSK receiver.



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- In this case, we have  $T=2T_b$  and  $E=2E_b$
- Hence, the probability of error is given by

$$P_e = \frac{1}{2} \exp\left(-\frac{E_b}{N_0}\right)$$

Detecting regular BPSK needs a coherent detector, requiring a phase reference

DPSK needs no such thing. The only reference is the previous bit which is readily available



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